Operating Instructions

IO-Link Master with EtherNet/IP Interface
StandardLine
4 Ports
IP 65 / IP 66 / IP 67

AL1120

HW Revision: AA, AB
Firmware: 2.3.x
LR DEVICE: 1.5.0.x

English

7391219 / 04 09 / 2019

Contents

1 Preliminary note

Content

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1.1 Legal and copyright information

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1.2 Purpose of the document

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This document is only for device types "IO-Link master - EtherNet/IP gateway (StandardLine) 4 port IP 65 / IP 66 / IP 67" (art. no.: AL1120).

It is part of the device and contains information about the correct handling of the product.

► Read this document before using the device.

► Keep this document during the service life of the device.

1.3 Explanation of Symbols

34171

WARNING!
Death or serious irreversible injuries may result.

CAUTION!
Slight reversible injuries may result.

NOTICE!
Property damage is to be expected or may result.

Important note
Non-compliance can result in malfunction or interference

Information
Supplementary note

► ... Request for action

> ... Reaction, result

→ ... "see"

abc Cross-reference

123 Decimal number
0x123 Hexadecimal number
0b010 Binary number

[...] Designation of pushbuttons, buttons or indications

1.4 Modification history

52841

Version	Topics	Date
00	New creation of document	05 / 2018
01	Correction: IoT Core	05 / 2018
02	Update to firmware 2.2.x ▪ Correction: description of NET status LED ▪ Correction: description of flags SENS PWR and AUX PWR ▪ Correction: description of IOL status LED ▪ Added: set RPI ▪ Extended: description of EtherNet/IP features	11 / 2018
03	Update to firmware 2.3.x ▪ Added: Configure Explicit PD Mode	04 / 2019
04	Correction: Technical data - Max. current load per output	09 / 2019

2 Safety instructions

Content

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2.1 General

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The plant manufacturer is responsible for the safety of the plant in which the device is installed.

If the device is used in a way that is not intended by the manufacturer, the protection supported by the device may be impaired.

Non-observance of the instructions, operation which is not in accordance with use as prescribed below, wrong installation or incorrect handling can affect the safety of operators and machinery.

- ► Observe these operating instructions.
- ► Adhere to the warning notes on the product.

2.2 Required background knowledge

34185

This document is intended for specialists. Specialists are people who, based on their relevant training and experience, are capable of identifying risks and avoiding potential hazards that may be caused during operation or maintenance of the product.

The document contains information about the correct handling of the product.

2.3 Safety symbols on the device

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General warning
Observe instructions in chapter "Electrical connection" (→ **Electrical connection** (→ S. 13))!

2.4 Tampering with the unit

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WARNING!

Tampering with the unit.

> In case of non-compliance:
  - Possible affects on safety of operators and machinery
  - Expiration of liability and warranty

- ► Do not open the devices!
- ► Do not insert any objects into the devices!
- ► Prevent metal foreign bodies from penetrating!

3 Intended use

Content

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3.1 Permitted use

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The IO-Link master serves as a gateway between intelligent IO-Link devices and the EtherNet/IP network. The device is designed for use without a control cabinet in the food industry.

3.2 Prohibited use

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The device may not be used beyond the limits of the technical data (→ **Technical data** (→ S. 54))!

4 Function

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4.1 Communication, parameter setting, evaluation

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4.1.1 IO-Link

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The device offers the following IO-Link functions:

- IO-Link master (IO-Link revision 1.0 and 1.1)
- 4 IO-Link ports for connection of IO-Link devices
- Provision of process data of the connected IO-Link devices for LR SMARTOBSERVER monitoring software (→ www.ifm.com)

4.1.2 EtherNet/IP

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The device offers the following EtherNet/IP functions:

- EtherNet/IP Device
- 2 port switch for access to the EtherNet/IP interface
- Gateway for transmission of the process and parameter data between the connected IO-Link devices and the higher-level EtherNet/IP controller
- Min. cycle time: 1 ms (RPI)
- Connection classes: 1, 3
- Connection Application types: Exclusive Owner, Input Only, Listen Only Connections
- UCMM supported
- Predefined standard objects:
  - Identity Object (0x01)
  - Message Router Object (0x02)
  - Assembly Object (0x04)
  - Connection Manager (0x06)
  - DLR Object (0x47)
  - QoS Object (0x48)
  - TCP/IP Interface Object (0xF5)
  - Ethernet Link Object (0xF6)
- Supported protocols: DHCP, BOOTP, ACD, DLR
- Device description: EDS file

4.1.3 Parameter setting

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The device provides the following configuration options:

- Parameter setting of the IO-Link master of the AL1120 with parameter setting software LR DEVICE and/or EtherNet/IP projection software
- Parameter setting of the connected IO-Link devices (sensors, actuators) with parameter setting software LR DEVICE and/or EtherNet/IP projection software
- Storage of parameter sets of the connected IO-Link devices for automatic recovery (data storage)

4.1.4 Visual indication

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The device has the following visual indicators:

- Status and error indication of the gateway, of the EtherNet/IP connection and of the system
- Status display of the voltage supply
- Status and activity display of the Ethernet connection
- Status, error and short circuit/overload indication of the IO-Link ports

4.2 Digital inputs

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The device has 4 additional digital inputs (type 2 according to EN 61131-2).

The digital inputs are on pin 2 of the IO-Link ports X01...X04.

All inputs refer to the potential of the device supply (pin 3).

4.3 IO-Link supply

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The device has 4 supplies for IO-Link devices.

The IO-Link ports X01...X04 are ports class A.

Every supply provides short circuit monitoring.

The device ensures fire protection for the connected IO-Link devices by providing a power-restricted circuit at the IO-Link ports (according to IEC61010-1 and Class 2 according to UL1310).

5 Mounting

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5.1 Mount the device

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- ► Disconnect the system from power before installation.
- ► For installation choose a flat mounting surface.
- ► Please observe the maximum tightening torque.

► Fix the unit to the mounting surface using 2 M5 mounting screws and washers.
  - Tightening torque: 1.8 Nm

► Ground the unit via the two mounting screws of the upper mounting lugs.

6 Electrical connection

Content

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6.1 Notes

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A qualified electrician must connect the unit.

► The national and international for regulations setting up electrical equipment must be complied with.

The unit is only suitable for operation using SELV/PELV voltages.

► Please note the information concerning IO-Link wiring!

This unit contains components that may be damaged or destroyed by electrostatic discharge (ESD).

► Please observe the required precautions against electrostatic discharge!

The IP rating of the overall system depends on the protection ratings of the individual devices, the applied connection elements and the corresponding protective caps.

► Provide cables with a strain relief depending on the mounting conditions to avoid excessive strain on the installation points and the M12 connections.

► Ensure correct fit and proper assembly of the M12 connecting parts. If these instructions are not complied with, the specified protection rating cannot be guaranteed.

For UL applications:

► To connect the IO-Link master and the IO-Link devices, only use UL-certified cables of the CYJV or PVVA category with a minimum temperature of 80 °C (75 °C in case of maximum ambient temperature of 40 °C).

Wiring: → **Technical data** (→ S. 54)

By means of basic insulation according to EN61010-1, the circuits are separated from each other and from device surfaces that could be touched (secondary circuit with 30 V DC maximum, supplied from mains circuit up to 300 V overvoltage category II).

By means of basic insulation according to EN61010-1, the communication interfaces are separated from each other and from device surfaces that could be touched (secondary circuit with 30 V DC maximum, supplied from mains circuit up to 300 V overvoltage category II). They are designed for network environment 0 according to IEC TR62102.

6.2 Ethernet ports

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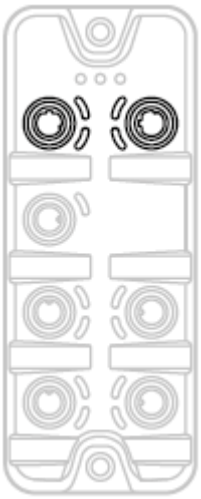

- ► Connect the unit via the M12 socket X21 and/or X22 with the EtherNet/IP network (e.g. EtherNet/IP PLC, additional EtherNet/IP device)
  - Tightening torque: 0.6...0.8 Nm
- ► Connect the unit via the M12 socket X21 and/or X22 to the industrial Ethernet network (e.g. laptop/PC with installed parameter setting software LR DEVICE, laptop/PC with installed monitoring software LR SMARTOBSERVER)
  - Tightening torque: 0.6...0.8 Nm
- ► For the connection, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ S. 52)).
- ► Cover the unused sockets with M12 protective caps (art no. E73004).
  - Tightening torque 0.6...0.8 Nm

6.3 IO-Link ports

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The IO-Link ports of the AL1120 meet the requirements of the IO-Link specifications 1.0 to 1.1.2.

► Please note the information concerning IO-Link wiring!

► Cover unused sockets with M12 protective caps (art. no.: E73004).

- Tightening torque 0.6...0.8 Nm

6.3.1 Connect IO-Link devices for Class A operation

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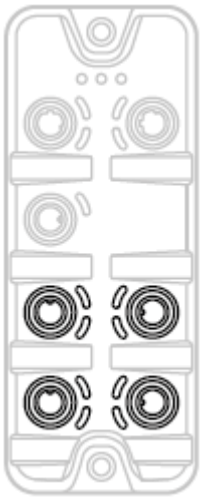
Wiring information:

- The connected IO-Link devices must be supplied exclusively via the IO-Link master.
- The additional digital inputs IO-Link ports X01...X04 (pin 2) have a type 2 behaviour according to the standard EN61131-2. The connected electronics must be electrically suited for this.



► Connect the connectors of the IO-Link devices with the M12 sockets of the IO-Link ports X01...X04.

- Tightening torque: 0.6...0.8 Nm
- Maximum cable length per IO-Link port: 20 m

► To connect the devices, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ S. 52)).

6.3.2 Connect IO-Link devices for Class B operation

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Notes on wiring:

- For Class B operation, the IO-Link device must be supplied with an additional auxiliary voltage UA using a Y connection cable.

WARNING!

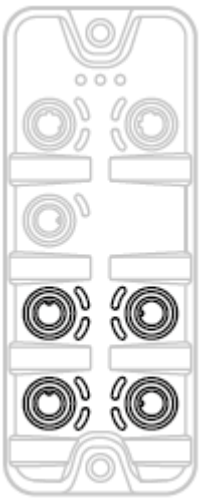
Non-compliance with the electrical separation of the circuits

> Risk of fire!

► Ensure that the external supply UA is galvanically separated from the circuit of the IO-Link Master by assuring basic insulation (according to IEC 61010-1, secondary circuit with 30 V DC maximum, supplied from mains circuit up to 300 V of overvoltage category II).

► Ensure that the IO-Link devices and the connection technology support the galvanic separation.

In case of operation as port class B, the additional digital input of the IO-Link port (pin 2) is not available!



► Connect the connectors of the IO-Link devices via a Y connection cable with the M12 sockets of the IO-Link ports X01...X04.

► Connect the Y cable to 24 V DC (20...30 V SELV/PELV)

  ▪ Tightening torque: 0.6...0.8 Nm

► To connect the devices, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ S. 52))!

6.4 Connect the device

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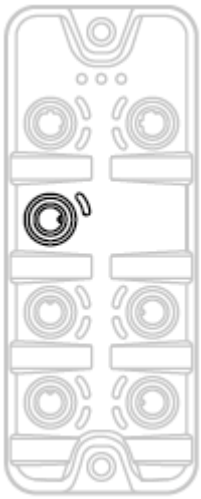

- ► Disconnect power.
- ► Connect the IO-Link Master via M12 socket X31 to 24 V DC (20...30 V SELV/PELV; according to EN61010-1, secondary circuit with maximum 30 V DC supplied by mains circuit up to 300 V of overvoltage category II).
  - Tightening torque: 0.6...0.8 Nm
  - Maximum cable length: 25 m
- ► To connect the device, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ S. 52)).

When using cable length greater than 25 m keep in mind the voltage drop as well as the required minimum voltage supply of 20 V!

7 Operating and display elements

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7.1 Overview

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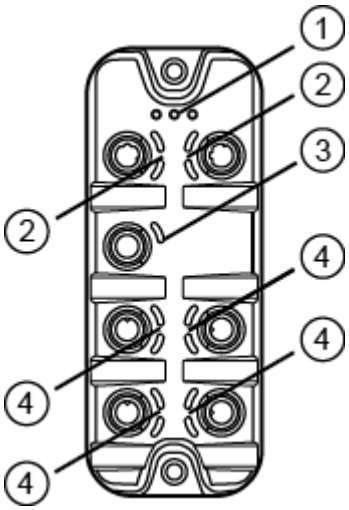

1. Status LEDs RDY, NET and MOD
   → **Status LEDs** (→ S. 19)
2. Status LEDs LNK and ACT of the EtherNet/IP ports 1 (X21) and 2 (X22)
   → **Ethernet interface** (→ S. 19)
3. Status LED US of the power supply (X31)
   → **Voltage supply** (→ S. 20)
4. Status LEDs IOL and DI of the IO-Link ports Class A (X01...X04)
   → **IO-Link ports (Class A)** (→ S. 20)

7.2 LED indicators

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The device only has the following LED indicators:

7.2.1 Status LEDs

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The RDY LED indicates the status of the gateway.
The NET LED (Network Status) indicates the status of the network.
The MOD LED (Module Status) indicates the status of the EtherNet/IP module.

Status LED			Description
RDY	green	on	Status: OK
		flashes 5 Hz	Status: Error
		flashes (200 ms on, 800 ms off)	Status: Firmware update is running
		off	Status: Gateway not running or gateway booting
NET	green / red	off	Not powered or powered, but IP address not yet configured
		flashes	Device self-testing
	green	flashes	No connection: no CIP connection established and a Exclusive Owner connection has not timed out
		on	Connection: at least one CIP connection established and an Exclusive Owner connection has not timed out
	red	flashes	Connection timeout: an Exclusive Owner connection has timed out
		on	Duplicate IP address: IP address aready in use
MOD	green / red	off	No voltage or voltage too low
		flashes	Device self-testing
	green	flashes	Standby: device not yet configured (no IP address)
		on	Operational
	red	flashes	Major recoverable fault (e.g. incorrect configuration)
		on	Major unrecoverable fault (e.g. module failed)

7.2.2 Ethernet interface

34348

Each Ethernet interface (X21, X22) has 2 LEDs (LNK and ACT). The LEDs indicate the status of the Ethernet connection.

Status LED			Description
LNK	green	on	Ethernet connection established
		off	No Ethernet connection
ACT	yellow	flashes	Data is transmitted via the Ethernet interface.
		off	No data transmission

7.2.3 Voltage supply

34191

The interface for voltage supply (X31) has the LED that is marked as US. The LED indicates the status of the voltage supply.

Status LED			Description
US	green	on	The supply voltage Us is applied.
		off	No supply voltage is applied or the applied supply voltage is too low.

7.2.4 IO-Link ports (Class A)

34074

Each IO-Link port Class A has 2 LEDs marked as IOL and DI. The LEDs indicate the status of the IO-Link port.

Status LED			Description
IOL	yellow	off	Port configured as DI / DO: pin 4 (C/Q) = OFF
		on	Port configured as DI / DO: pin 4 (C/Q) =ON
	green	flashes 1 Hz	Port configured as IO-Link: no IO-Link device detected
		flashes 2 Hz	Port configured as IO-Link: PROOPERATE state
		on	Port configured as IO-Link: OPERATE state
	red	flashes 2 Hz	Port configuration error or short circuit or overload (US)
		on	Transmission error
DI	yellow	off	Digital input : pin 2 (DI) = OFF
		on	Digital input: pin 2 (DI) = ON

8 Set-up

Content

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When the supply voltage has been switched on, the AL1120 starts with the factory settings. The display elements signal the current operating status (→ **Operating and display elements** (→ S. 18)).

To enable parameter setting of the AL1120, the fieldbusinterface of the network environment must be configured correspondingly.

► Configure the fieldbus interface (ports X21 / X22) (→ **Fieldbus: Configure IP settings** (→ S. 28) or → **Integrate the AL1120 into the EtherNet/IP project** (→ S. 37)).

> The fieldbus interface has valid IP settings.

> The user can set the parameters of the AL1120.

Further steps:

- Optional: Update the firmware of the AL1120 (→ **Firmware update** (→ S. 49)).
- Set the parameters of the AL1120 (→ **Configuration** (→ S. 23)).

8.1 Read device and diagnostic information

34216

In order to read the diagnostic information about the current device status via the web interface:

► Connect laptop/PC and AL1120 via the Ethernet internet.

► Start web browser.

► Enter the IP address of the AL1120 into the address field of the browser and press [ENTER] to confirm.

> Web browser shows the web interface of the device.

> The page shows the following data:

- Table with connected IO-Link devices

Name	Description
[Port]	Number of the IO-Link interface
[Mode]	Operating mode of the IO-Link interface
[Comm. Mode]	Baud rate of the IO-Link interface
[MasterCycleTime]	Cycle time
[Vendor ID]	ID of the manufacturer of the IO-Link device
[Device ID]	ID of the IO-Link device
[Name]	Article number of the IO-Link device ▪ For ifm articles: This article number is stored along with a link to the produkt page on the ifm website.
[Serial]	Serial number of the IO-Link device
[LR Mode / Interval]	Cycle time for the communication with the SmartObserver

- Diagnostic information of the device

Name	Description
[SW-Version]	
[Current]	Current (in mA)
[Voltage]	Voltage (in mV)
[Short Circuit]	Number of detected short circuits
[Overload]	Number of detected overloads
[Undervoltage]	Number of detected under voltages
[Temperature]	Device temperature (in °C)

- Version information of the installed firmware components

Name	Description
[Firmware]	Firmware version
[Container]	Version of the firmware container
[Bootloader Version]	Version of the boot loader
[Fieldbus Firmware]	Version of the EtherNet/IP firmware

9 Configuration

Content

33858

9.1 LR DEVICE

Content

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On delivery, the AL1120 is configured with the factory settings (→ **Factory Settings** (→ S. 51)).

Required software: LR DEVICE (1.5.0.x or higher) (art.-no.: QA0011/QA0012)

9.1.1 Remarks

Content

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Offline parameter setting

34060

The AL1120 supports the offline parameter setting. In this context, the user creates and stores a configuration for the IO-Link master and the connected IO-Link devices without being connected to the AL1120 (OFFLINE mode). The configuration created in this way can be stored as a file (*.lrp) and loaded to the AL1120 and activated at a later date.

Further information about offline parameter setting: → Operating instructions LR DEVICE

VPN connection

34382

An active VPN connection blocks the access of the parameter setting software LR DEVICE to the EtherNet/IP interface of the AL1120.

► Deactivate the VPN connection in order to be able to access the AL1120 with the LR DEVICE.

9.1.2 IoT: Configure access rights

34046

The access rights define which instance may read and / or write the parameter data, process data and event/diagnostic messages.

In order to configure the access rights to the IO-Link master:

► Select [IoT] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Access Rights]	The access rights to the parameter data, process data and the event/diagnostic messages of the IO-Link master as well as the connected IO-Link devices	[EtherNet/IP + IoT]	▪ EtherNet/IP and IoT Core have read and write access rights to parameters and process data ▪ EtherNet/IP and <IoT Core> have read access rights to events/alarms
		[EtherNet/IP + IoT (read-only)]	▪ EtherNet/IP has read and write access rights to parameters and process data ▪ EtherNet/IP has read access rights to events/alarms ▪ IoT Core only has read access rights to parameters, process data and events/alarms
		[IoT only]	▪ IoT Core has read and write access rights to parameters and process data ▪ IoT has read access rights to events/alarms ▪ EtherNet/IP has no access rights

► Save changed values on the device.

If the parameter [Access rights] is set to [EtherNet/IP + IoT] via IoT and EtherNet/IP projection, then the parameter values set in the EtherNet/IP projection software apply.

If the parameter [Access rights] is set to [IoT only] via IoT, then set the parameter [Access rights] to [Keep settings] in the EtherNet/IP projection software.

Changes of the parameter [Access Rights] are only effective after restarting the device (→ **Firmware: Reboot the device** (→ S. 34))

9.1.3 IoT: Configure the interface to LR AGENT or LR SMARTOBSERVER

34048

To enable transfer of process data from the IO-Link master to LR AGENT or LR SMARTOBSERVER, the interface has to be configured accordingly.

► Select [IoT] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[IP address LR Agent or SMARTOBSERVER]	IP address of LR AGENT or LR SMARTOBSERVER	Factory setting: 255.255.255.255	
[Port LR Agent or SMARTOBSERVER]	Port number that is used to send process data to LR AGENT or LR SMARTOBSERVER	0 ... 65535	Factory setting:: 35100
[Interval LR Agent or SMARTOBSERVER]	Cycle time for the transfer of the process data to LR AGENT or LR SMARTOBSERVER (value in milliseconds)	[Off]	no transfer
		500 ... 2147483647	500 ms ... 2147483647 ms
[Application Tag]	Source identifier of the IO-Link master in the structure of LR AGENT or LR SMARTOBSERVER (String32)	Factory setting: AL1120	

After changing the parameter [Port LR Agent or SMARTOBSERVER] or [Application Tag], it may take 120 seconds before the device establishes a new TCP connection.

To prevent the delay:

► Reboot the device after changing the the parameter.

► Save changed values on the device.

9.1.4 Fieldbus: Configure IP settings

54692

For communication with the EtherNet/IP network, the EtherNet/IP interface must be configured.

► Select [Fieldbus] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[DHCP]	Enable / disable the DHCP client of the device	[Static IP]	IP parameters are set by the user
		[DHCP]	IP parameters are set by a DHCP server in the network.
		[BOOTP]	IP parameters are set via the Bootstrap Protocol (BOOTP)
[IP address]*	IP address of the EtherNet/IP port	Factory setting: 192.168.1.250	
[Subnet mask]*	Subnet mask of the IP network	Factory setting: 255.255.255.0	
[Default gateway IP address]*	IP address of the gateway	Factory setting: 0.0.0.0	
[Host name]	Name of the device in the EtherNet/IP network	e.g. al1xxx	
[MAC address]	MAC address of the device	The value is firmly set.	
[Fieldbus firmware]		e.g. 3.4.04 (EtherNet/IP Adapter)	

* ... Parameter can only be edited if parameter [DHCP] = [Static IP]

► Save changed values on the device.

9.1.5 Fieldbus: set the configuration mode

54693

The AL1120 supports the EtherNet/IP configuration modes "top-down" and "independent". Additionally, the user can configure the length of the transmitted process data and select the required connection types.

► Select [Fieldbus] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Configuration]*	EtherNet/IP configuration mode	Independent mode off	Configuration via fieldbus PLC
		Independent mode on	Configuration via AL1120
[Process data length]*	Length of process data per IO-Link port	2 bytes input 2 bytes output	2 bytes input data, 2 bytes output data
		4 bytes input 4 bytes output	4 bytes input data, 4 bytes output data
		8 bytes input 8 bytes output	8 bytes input data, 8 bytes output data
		16 bytes input 16 bytes output	16 bytes input data, 16 bytes output data
		32 bytes input 32 bytes output	32 bytes input data, 32 bytes output data
[Swap]*	Sequence of bytes in the data word	off	as Array of Bytes
		on	as Integer16 value; during an update of the process data, the bytes are exchanged
[Explicitpdmode]**	Enable / disable explicit PD mode and select the process data to be transmitted (connection types)	Explicit process data mode off	Explicit PD mode disabled
		Explicit process data mode with IO-Link I/O + Acyclic + Diag	Explicit PD mode enabled: IO-Link inputs /outputs, acyclic data and diagnostic data are transmitted
		Explicit process data mode with IO-Link I/O + Acyclic	Explicit PD mode enabled: IO-Link inputs/outputs and acyclic data are transmitted
		Explicit process data mode with IO-Link I/O	Explicit PD mode enabled: IO-Link inputs/outputs are transmitted

* ... Parameter can only be changed if the EtherNet/IP controller is disconnected
** ... Parameter only valid if [Configuration] = [Independent mode on]

► Save changed values on the device.

9.1.6 IO-Link ports: Activate data transfer to LR AGENT or LR SMARTOBSERVER

33690

The user can decide separately for each IO-Link port whether the process data of the connected IO-Link devices should be transferred to LR AGENT or LR SMARTOBSERVER.

To transfer process data the interface to the LR AGENT or LR SMARTOBSERVER has to be correctly configured (→ **IoT: Configure the interface to LR AGENT or LR SMARTOBSERVER** (→ S. 27)).

To activate / deactivate data transfer:

► Select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Transmission to LR Agent or SMARTOBSERVER]	Transfer of process data of the connected IO-Link device to LR AGENT oder LR SMARTOBSERVER	[Disabled]	Transfer process data
		[Enabled]	Don't transfer process data

► Save changed values on the device.

9.1.7 IO-Link ports: Configure operating mode

33694

The IO-Link ports X01...X04 of the device support the following operating modes:

- Digital input (DI): binary input signal at pin 4 (C/Q) of the IO-Link port
- Digital output (DO): binary output signal at pin 4 (C/Q) of the IO-Link port
- IO-Link: IO-Link data transfer via pin 4 (C/Q) of the IO-Link port

The user can set the operating mode separately for each IO-Link port.

To set the operating mode of an IO-Link port:

► Select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Mode]	Operating mode of the IO-Link port	[Disabled]	Port deactivated
		[DI]	Operation as digital input
		[DO]	Operation as digital output
		[IO-Link]	Operation as IO-Link interface
[Cycle time actual]**	Current cycle time of the data transfer between IO-Link master and IO-Link device on the port (value in microseconds)	Parameter can only be read	
[Cycle time preset]*	Cycle time of the data transfer between the IO-Link master and the IO-Link device at the port (value in microseconds)	0	The device automatically sets the fastest possible cycle time.
		1 ... 132800	1 microsecond ... 132800 microseconds
[Bitrate]**	Current transmission rate of the data transfer between the IO-Link master and the IO-Link device on the port	Parameter can only be read	

* ... Parameter only available if [Mode] = [IO-Link]
** ... Parameter only visible if the IO-Link device is connected to the IO-Link port.

► Save changed values on the device.

9.1.8 IO-Link ports: Set the device validation and data storage

33697

The user can choose how the IO-Link ports are to behave with regard to the device validation and the storage / recovery of parameter data of the connected IO-Link device.

The following options are available:

Option	Validation of the IO-Link device	Storage of the parameter values	Recovery of the parameter values
[No check and clear]	no	no	no
[Type compatible V1.0 device]	yes, test the compatibility with IO-Link standard V1.0	no	no
[Type compatible V1.1 device]	yes, test the compatibility with IO-Link standard V1.1	no	no
[Type compatible V1.1 device with Backup + Restore]	yes, test the compatibility with IO-Link standard V1.1 and identity of design (vendor ID and device ID)	yes, automatic storage of the parameter values; changes of the current parameter values will be stored	yes, recovery of the parameter values when connecting an identical IO-Link device with factory settings
[Type compatible V1.1 device with Restore]	yes, test the compatibility with IO-Link standard V1.1 and identity of design (vendor ID and device ID)	no, there is no automatic storage changes of the current parameter values will not be stored	yes, recovery of the parameter values when connecting an identical IO-Link device with factory settings

The options only apply if the IO-Link port is in the operating mode "IO-Link".

For options [Type compatible V1.1 device with Backup + Restore] and [Type compatible V1.1 device with Restore]: If the vendor ID and device ID are changed in the online mode, the data memory will be deleted and a new backup of the parameter values of the connected IO-Link device will be created in the IO-Link master.

To configure the device validation and the data storage:

► select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Validation / Data Storage]	Supported IO-Link standard and behaviour of the IO-Link master when connecting a new IO-Link device at port x (x = 1...4)	[No check and clear]	
		[Type compatible V1.0 device]	
		[Type compatible V1.1 device]	
		[Type compatible V1.1 device with Backup + Restore]	
		[Type compatible V1.1 device with Restore]	
[Vendor ID]	ID of the manufacturer that is to be validated	0...65535	Factory setting: 0# ifm electronic: 310
[Device ID]	ID of the IO-Link device that is to be validated	0...16777215	Factory setting: 0

► Save changed values on the device.

9.1.9 IO-Link Ports: Set fails-safe values

34329

For the configuration mode "Independent" the user can set fail-safe values for the outputs of IO-Link ports X01...X04. The fail-safe values will be activated in case of an interuption of the EtherNet/IP conection.

To set the fail-safe values:

► Select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Fail-safe digital out]*	Fail-safe value of the output for operating mode "Digital Output (DO)"	[Reset]	OFF
		[Old]	old value
		[Set]	ON
[Fail-safe IO-Link]*	Fail-safe value of the output for operating mode "IO-Link"	[Off]	no Fail-safe
		[Reset]	Fail-safe: OFF
		[Old	Fail-safe: old value
		[Pattern]	Fail-safe: byte pattern

* ... Parameter only changeable, if the connection to the EtherNet/IP controller is closed

► Save changed values on the device.

9.1.10 Info: Show device information

34065

To read the general information of the ifm IO-Link master:

► Select [Info] menu.

> The menu page shows the current settings.

Name	Description	Possible values
[Product code]	Article number of the IO-Link master	AL1120
[Device family]	Device family of the IO-Link master	IO-Link master
[Vendor]	Vendor	ifm electronic gmbh
[SW-Revision]	Firmware of the IO-Link master	
[HW revision]	Hardware version of the IO-Link master	
[Bootloader revision]	Bootloader version of the IO-Link master	
[Serial number]	Serial number	

9.1.11 Firmware: Reset device to factory settings

33838

When the IO-Link master is reset, all parameters are set to the factory settings:
To reset the device to factory settings:

► Select [Firmware] menu.
> The menu page shows the current settings.
► Click on [Factory Reset] to reset the device.
> LR DEVICE sets the device to the factory settings.

9.1.12 Firmware: Reboot the device

33832

When rebooting the device, all settings are kept.
To restart the AL1120:

► Select [Firmware] menu.
> The menu page shows the current settings.
► Click on [Reboot] to reboot the device.
> LR DEVICE reboots the ifm IO-Link master.

9.1.13 Configure IO-Link devices

33856

To configure the IO-Link devices connected to the device with the LR DEVICE parameter setting software:

Requirements:

> IO-Link master is correctly installed and connected to the LR DEVICE parameter setting software.

> The IO-Link device is correctly connected to the AL1120.

> Operating mode of the IO-Link port is "IO-Link" (→ **IO-Link ports: Configure operating mode** (→ S. 31)).

> IoT has write access rights to the IO-Link master (→ **IoT: Configure access rights** (→ S. 26)).

1 Select IO-Link master

► Start LR DEVICE.

► Update IODD file library
OR:
Import IODD file of the IO-Link device manually.

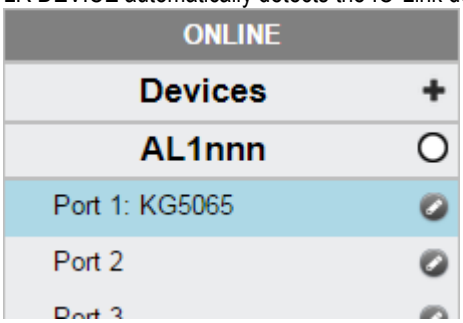
► Scan network for devices.

> LR DEVICE detects IO-Link master.

2 Add IO-Link device

► Under [ONLINE]: Click on the required IO-Link master.

> LR DEVICE automatically detects the IO-Link devices connected to the IO-Link master (e.g. ifm sensor KG5065).



3 Configure IO-Link device

► Mouse click on the port to which the IO-Link device is connected.

> LR DEVICE reads and shows the current parameter values of the IO-Link device.

► Configure IO-Link device.

Information about the available parameters of the IO-Link device: → IO Device Description (IODD) of the IO-Link device

► Save the changed configuration on the IO-Link device.

9.2 EtherNet/IP

Content

34391

On the fieldbus side, the device can be configured with any EtherNet/IP compatible projection software.

The information in the following sections refers to the EtherNet/IP projection software RSLogix 5000.

9.2.1 Registration of the EDS file

34324

ifm provides an EDS file to integrate the AL1120 in a EtherNet/IP projection software. The user can download the EDS file from the ifm website (→ www.ifm.com). In the EDS file, all parameters, process data, and their valid value ranges are defined.

To add the AL1120 to the device catalogue of RSLogix5000:

► Download the EDS file of the AL1120 from the ifm website.

► Start RSLogix5000.

► Select [Tools] > [EDS Hardware Installation Tool].

> EDS Wizard appears.

► Register the downloaded EDS file of the AL1120 with the EDS Wizard.

> EDS Wizard installs the EDS file and adds the AL1120 to the device catalogue.

9.2.2 Integrate the AL1120 into the EtherNet/IP project

34392

The device is integrated as module of an I/O scanner in the EtherNet/IP project.

Requirements:

> The EDS file of the AL1120 is installed (→ **Registration of the EDS file** (→ S. 36)).

1 Create/open EtherNet/IP project

► Start RSLogix 5000.

► Create new EtherNet/IP project.
OR
Open an existing EtherNet/IP project.

2 Configure EtherNet/IP PLC and IO scanner

► Select and configure EtherNet/IP controller and IO scanner.

> EtherNet/IP project includes a EtherNet/IP controller and an IO scanner.

3 Integrate AL1120 in project

► In the Controller Organizer: Right mouse click on the IO scanner.

> Context menu appears.

► In the context menu: Select [New Module...].

> The window [Select Module Type] appears.

► Select AL1120 and click on [Create].

> The [New Module] window appears.

► Enter name and IP address of the AL1120.

► Click on [OK] to adopt the entered values.

> RSLogix 5000 adds AL1120 as sub-element of the IO scanner to the project.

4 Save the project

► Save EtherNet/IP project

9.2.3 Set connection types and RPI

34407

The IO-Link master supports different connection types (→ **Supported connection types** (→ S. 58)). The user can choose which object instances of the input assembly and the output assembly are used. This makes it possible to adapt the size of the transmitted and received data. Additionaly the Request Package Interval (RPI) can be selected.

To set the connection type:

Requirements:

> AL1120 is correctly integrated into the EtherNet/IP project (→ **Integrate the AL1120 into the EtherNet/IP project** (→ S. 37)).

1 Open the module properties

► In the Controller Organizer: Double-click on the IO-Link master node

> Dialogue window appears.

2 Set connection type

► Click on [Change...].

> The [Module Definition] dialogue window appears.

► Select the required connection type from the list [Connections].

► Click on [OK] to apply the changes.

3 Change RPI

► Click on [Connection] tab.

> The connection settings appear.

► Select required time value from [RPI] list.

► Click on [OK] to apply the changes.

9.2.4 Configure AL1120

34357

The AL1120 is configured via the controller tags.

Requirements:

> AL1120 is correctly integrated in the EtherNet/IP project (→ **Integrate the AL1120 into the EtherNet/IP project** (→ S. 37)).

1 Open controller tags

► In the Controller Organizer: Double click on [Controller Name_of_Project] > [Controller Tags]

> [Controller Tags] window appears.

► In the tree view: Click on [AL1120:C].

> Controller tags for the configuration of the device appear.

2 Configure AL1120

► Set the following controller tags as required:

Name	Description	Possible values	
[AL1120:C.Communication_Profile]	The access rights to the parameter data, process data and events/diagnostic messages of the IO-Link master and the connected IO-Link devices	0x00	EtherNet/IP + LineRecorder ▪ EtherNet/IP and LR DEVICE have read and write access rights to parameters and process data ▪ EtherNet/IP and LR DEVICE have read access rights to events/alarms
		0x01	EtherNet/IP + LineRecorder (ro) ▪ EtherNet/IP has read and write access rights to parameters and process data ▪ EtherNet/IP has read access rights to events/alarms ▪ LR DEVICE only has read access rights to parameters, process data and events/alarms
		0x02	EtherNet/IP only ▪ EtherNet/IP has read and write access rights to parameters and process data ▪ EtherNet/IP has read access rights to events/alarms ▪ LR DEVICE has no access rights (parameters, process data, events/alarms, web interface, firmware update)
		0x03	Continue in Use Case previous setting is valid
[AL1120:C.Port_Process_Data_Size]	Length of the process input data and process output data	0x00	2 bytes input, 2 bytes output
		0x01	4 bytes input, 4 bytes output
		0x02	8 bytes input, 8 bytes output
		0x03	16 bytes input, 16 bytes output
		0x04	32 bytes input, 32 bytes output

► Save EtherNet/IP project

9.2.5 Configure IO-Link ports

34365

The IO-Link ports are configured via the controller tags. The user can configure each IO-Link port separately.

To configure the IO-Link ports:

Requirements:

> AL1120 is correctly integrated in the EtherNet/IP project (→ **Integrate the AL1120 into the EtherNet/IP project** (→ S. 37)).

1 Open controller tags

► In the Controller Organizer: Double click on [Controller Name_of_Project] > [Controller Tags]

> [Controller Tags] window appears.

► In the tree view: Click on [AL1120:C].

> Controller tags for the configuration of the device appear.

2 Configure IO-Link ports

► Configure the following tags for each IO-Link port at will:

Name	Description	Possible values	
[AL1120:C.Port_Mode_Port_x]	Operating mode of the IO-Link port	0x00	Interface deactivated
		0x01	Operation as digital input (DI)
		0x02	Operation as digital output (DO)
		0x03	Operation as IO-Link interface
[AL1120:C.Port_Cycle_Time_Port_x]	Cycle time of the data transmission between the IO-Link master and the IO-Link device	0x00	The device automatically sets the fastest possible cycle time
		0x01	2 milliseconds
		0x02	4 milliseconds
		0x03	8 milliseconds
		0x04	16 milliseconds
		0x05	32 milliseconds
		0x06	64 milliseconds
		0x07	128 milliseconds
[AL1120:C.Swap_Port_x]	Visualisation of the process data (EtherNet/IP uses Little Endian Format (Intel), IO-Link uses Big Endian Format (Motorola))	0x00	Byte swapping for IO-Linkdata deactivated
		0x01	Byte swapping for IO-Linkdata activated
[AL1120:C.Validation_Data_Storage_Port_x]	Supported IO-Link standard and behaviour of the IO-Link master when connecting new IO-Link devices to the IO-Link port	0x00	No validation
		0x01	Type compatible V1.0 device
		0x02	Type compatible V1.1 device
		0x03	Type compatible V1.1 device with Backup + Restore
		0x04	Type compatible V1.1 device with Restore
[AL1120:C.Vendor_ID_Port_x]	Vendor ID of the manufacturer of the device on the IO-Link port	0x0000...0xFFFF ifm electronic: 0x136	
[AL1120:C.Device_ID_Port_x]	Device ID of the device on the IO-Link port	0x000000...0xFFFFFF	

Name	Description	Possible values	
[AL1120:C.Fail_Safe_Mode_Port_x]	Fail-safe mode for output data when the EtherNet/IP connection is interrupted	0x00	No Failsafe
		0x01	Failsafe Reset Value
		0x02	Failsafe Old Value
		0x03	Failsafe with Pattern
[AL1120:C.Fail_Safe_Value_DO_Port_x]	Fail-safe value for the operating mode "digital output (DO)"	0x00	Failsafe Reset Value
		0x01	Failsafe Old Value
		0x02	Failsafe Set Value

x = 1...4

► Save EtherNet/IP project.

9.2.6 Configure IO-Link devices

34359

The AL1120 supports the configuration of the connected IO-Link devices from the EtherNet/IP projection software. For this, ifm offers the EtherNet/IP object "IO-Link Request" (→ **IO-Link requests (object class: 0x80)** (→ S. 95)). The object enables direct read and write access to IO-Link objects of the IO-Link device. The extent of the configurable parameters depends on the IO-Link device.

The following services are available:

Name	Description	Reference
Read request	Send a request to read an IO-Link object	→ **Read_ISDU** (→ S. 96)
Write request	Send a request to write an IO-Link object	→ **Write_ISDU** (→ S. 99)

Information for the execution of acyclic commands: → **Use acyclic services** (→ S. 46)
Available parameters of the IO-Link devices: → Operating instructions of the IO-Link device

9.2.7 Read cyclic input data

34360

The user can access the cyclic input data of the connected sensors and IO-Link devices via the controller tags of the AL1120.

To check the validity of the cyclic process data, evaluate the PQI byte (→ **Mapping: PQI** (→ S. 68)).

Even with an interruption of the fieldbus connection the PQI byte indicates that the process data is valid. This can have unintended impact on the control process.

► Take suitable measures to detect an interruption of the fieldbus connection.

To access the input data:

► Starting RSLogix5000.

► Open the EtherNet/IP project.

► In the project tree: Mouse click on [Controller Tags] > [AL1120.I]

> The window shows the data structure with cyclic input data ([AL1120.I:Data])

Mapping of the inputs to the data structure [AL1120.I:Data]: → **Cyclic data** (→ S. 63))

9.2.8 Write cyclic output data

34386

The user can access the cyclic output data of the connected actuators and IO-Link devices via the controller tags of the AL1120.

To check the validity of the cyclic process data, evaluate the PQI byte (→ **Mapping: PQI** (→ S. 68)).

Even with an interruption of the fieldbus connection the PQI byte indicates that the process data is valid. This can have unintended impact on the control process.

► Take suitable measures to detect an interruption of the fieldbus connection.

To access the cyclic output data:

► Starting RSLogix5000.

► Open the EtherNet/IP project.

► In the project tree: Mouse click on [Controller Tags] > [AL1120.O]

> The window shows the data structure with cyclic output data ([AL1120.O:Data])

Mapping of the outputs to the data structure [AL1120.C:O]: → **Cyclic data** (→ S. 63)).

9.2.9 Read diagnostic information and events

34338

Diagnostic and status information is a part of the cyclically transmitted process data. The input assembly includes the following information:

Byte	Content
2	Indication of short circuit/overload of the IO-Link ports X01...X04
3	Status indication of the voltage supply of the device
43	Port X01: Status information + events
58	Port X02: Status information + events
73	Port X03: Status information + events
88	Port X04: Status information + events

To access the cyclically transmitted diagnostic and status information:

► Starting RSLogix5000.

► Open a EtherNet/IP project.

► In the project tree: Mouse click on [Controller Tags] > [AL1120.I]

> The window shows cyclic input data (Input Assembly).

► Link diagnostic and status information with variables.

Mapping of the diagnostic and status information on the data structure [AL1120.C:I]: → **Cyclic data** (→ S. 63).

9.2.10 EtherNet/IP: Programmers' notes

34397

The programmer can access on the following data from the PLC application:

- Read device information of the AL1120
- Read diagnostics and alarms
- Set parameters of the connected IO-Link devices

The following sections show the available options.

Further information about the functional/operational blocks: → Help function of the EtherNet/IP projection software

Supported EtherNet/IP configuration modes

34383

The AL1120 supports the following EtherNet/IP configuration modes:

- **Top down**
  - Configuration of the EtherNet/IP slave with the EtherNet/IP projection software (Configuration Assembly)
  - EtherNet/IP plc transmitts the created configuration to the EtherNet/IP slave, where it is stored
- **Independent**
  - Configuration of the EtherNet/IP slave with LR DEVICE oder IoT core
  - Confiuration Assembly in EtherNet/IP project is not evaluated

Use acyclic services

34381

The AL1120 offers the following options to execute acyclic commands:

Command channels in cyclic process data

34318

Within the cyclic input and output data, special areas are available for the acyclic data transmission. Both read and write access can be implemented via the areas.

Principle of the command channels

34343

General process of an acyclic communication:

1 Write command request

- ► In the request channel: write requested command data (without [Trigger] bit)
- ► Set [Trigger] = 1.
- > Change of [Trigger] = 1 indicates a new command.
- > In the response channel: all bytes are set to 0.
- > Command processing is started.

2 Check status

- ► In the response channel: check [Handshake] bit.
- If [Handshake] <> 0: command processing completed, continue with step 3.
- If [Handshake] == 0: command is processed, repeat step 2.

3 Read command response

- ► In the response channel: read responsed user data.
- ► In the request channel: set [Trigger] = 0.

Acyclic port commands

34336

For the acyclic access to the configuration of the IO-Link ports of the AL1120, the following commands are available:

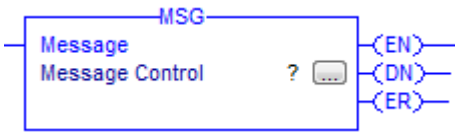
Command	Description	Reference
Set mode	Set the operating type of the IO-Link port	→ **Command 0x10 – Set mode** (→ S. 80)
Set Validation ID / Data Storage	Adjust the supported IO-Link standard and the behaviour of the IO-Link master when connecting a new IO-Link device to the IO-Link port	→ **Command 0x20 – Set validation ID / data storage** (→ S. 82)
Set fail-safe data pattern	Behaviour of the outputs when the EtherNet/IP connection is interrupted and setting of the corresponding fail-safe values	→ **Command 0x30 – Set fail-safe data pattern** (→ S. 84)

The port commands use the same mechanisms as the acyclic command channel (→ **Acyclic command channel** (→ S. 74)).

EtherNet/IP mechanisms for acyclic commands

34404

Acyclic commands can be executed with the EtherNet/IP command `Message (MSG)`.



Parameters of the available field bus objects: → **Field bus objects** (→ S. 86)

For detailed information about the `Message (MSG)` command: → Operating instructions RSLogix 5000

10 Maintenance, repair and disposal

Content

51990

The operation of the unit is maintenance-free.

► Dispose of the unit in an environmentally friendly way in accordance with the applicable national regulations when it is no longer used.

10.1 Cleaning process

51991

► Clean the surface of the unit when necessary.

► Do not use any caustic cleaning agents for this!

10.2 Firmware update

33826

The new firmware is installed via the device's web interface.

If the firmware update is not successful, deactivate all connections to the EtherNet/IP PLC, LR SMARTOBSERVER and LR DEVICE and repeat the process.

- ► Close connection to EtherNet/IP PLC.
- ► Set the parameter [IP address SmartObserver] to 255.255.255.255 or 0.0.0.0 (→ **IoT: Configure the interface to LR AGENT or LR SMARTOBSERVER** (→ S. 27)).
- ► Stop the LRAgent.LRDevice service in the Windows task manager.

After the firmware update check the settings of the LR SMARTOBSERVER interface!

To install a new firmware version on the device:

Requirements

> File with new firmware has been downloaded.

> Ethernet connection between laptop/PC and device is established.

1 Call up web interface

- ► Start web browser.
- ► Enter the following into the address field of the browser and press [ENTER] to confirm:
  `http://<IP address of the device>/web/update`

> Web browser shows the [Firmware Update] page.

2 Load new firmware to AL1120

- ► Click on [Select file].

> Dialogue window appears.

- ► Select the firmware file and click on [Open] in order to adopt the file.
- ► Click on [Submit] to start the firmware update.

> Firmware is being loaded to the device.

> After successful storage, the success message is displayed

3 Restart the device

- ► Click on [Restart device now] to restart the device.

> The status LED RDY flashes quickly.

> Firmware is updating.

- ► Follow the instructions in the browser.

10.3 Replace IO-Link device

34182

To replace an IO-Link device:

Requirement:

> IO-Link device is with factory settings.

> IO-Link device supports IO-Link standard 1.1 or higher.

1 Set data storage

► Set the following parameters of the IO-Link port:
Validation and Data Storage = [Type compatible V1.1 device with Restore]

► Save changes.

2 Replace IO-Link device

► Disconnect old IO-Link device from IO-Link master.

► Connect new IO-Link device with the same IO-Link port of the AL1120.

> IO-Link master copies parameter values from the data memory to the new IO-Link device.

11 Factory Settings

34591

In the factory settings, the device has the following parameter settings:

Parameter	Factory setting
[IP address]	192.168.1.250
[Subnet mask]	255.255.255.0
[IP gateway address]	0.0.0.0
[Host name]	blank
Data Storage	empty

12 Accessories

33870

List of accessories of AL1120: → www.ifm.com > Product page > Accessories

13 Appendix

Content

33879

13.1 Technical data

Content

34188

13.1.1 Application

33878

Application	
Application	I/O modules for field applications
Daisy-chain function	Communication interface

13.1.2 Electrical data

33808

Electrical data	
Operating voltage [V]	20...30 DC; (US; to SELV/PELV)
Current Consumption [mA]	300...3900; (US)
Protection class	III
Sensor supply US	
Max. current load total [A]	3.6

13.1.3 Inputs / outputs

34068

Inputs / outputs	
Total number of inputs and outputs	8; (configurable)
Number of Inputs and Outputs	Number of digital inputs: 8; Number of digital outputs: 4

13.1.4 Inputs

34069

Inputs	
Number of digital inputs	8; (IO-Link Port Class A: 4 x 2)
Switching level high [V]	11...30
Switching level low [V]	0...5
Digital inputs protected against short circuits	yes

13.1.5 Outputs

34053

Outputs	
Number of digital outputs	4; (IO-Link Port Class A: 4 x 1)
Max. current load per output [mA]	300
Short-circuit protection	yes

13.1.6 Interfaces

34586

Interfaces	
Communication interface	Ethernet; IO-Link
Communication interface	IO-Link; TCP/IP; EtherNet/IP
Ethernet	
Transmission standard	10Base-T; 100Base-TX
Transmission rate	10; 100
Protocol	TCP/IP; EtherNet/IP
Factory settings	▪ IP address: 192.168.1.250 ▪ Subnet mask: 255.255.255.0 ▪ Gateway IP address: 0.0.0.0 ▪ MAC address: see type label
IO-Link Master	
Transmission type	COM 1 / COM 2 / COM 3
IO-Link revision	V1.1
Number of ports class A	4

13.1.7 Operating conditions

34062

Operating conditions	
Applications	Indoor use
Ambient temperature [°C]	-25...60
Storage temperature [°C]	-25...85
Max. perm. relative air humidity [%]	90
Max. height above sea level [m]	2000
Protection rating	IP 65; IP 66; IP 67
Pollution Degree	2

13.1.8 Approvals / tests

33877

Approval / tests	
EMC	▪ EN 61000-6-2 ▪ EN 61000-6-4
MTTF [Years]	90

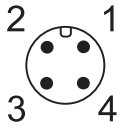
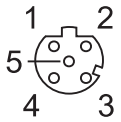
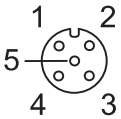
13.1.9 Mechanical data

34050

Mechanical data	
Weight [g]	294.5
Materials	Housing: PA; socket: brass nickel-plated

13.1.10 Electrical connection

34608

Voltage supply IN X31			
Connector	M12		
Wiring		1: 2: 3: 4:	+ 24 V DC (US) - GND (US) -
Ethernet IN / OUT X21, X22			
Connector	M12		
Wiring		1: 2: 3: 4: 5:	TX + RX + TX - RX - -
Process connection IO-Link Ports Class A X01...X04			
Connector	M12		
Wiring		1: 2: 3: 4: 5:	Sensor supply (US) L+ DI Sensor supply (US) L- C/Q IO-Link -

13.2 EtherNet/IP

Content

33674

13.2.1 Supported connection types

34410

Name	Configuration Assemby	Input Assembly - Instance	Output Assembly - Instance
Exclusive Owner IO-Acyc-Diag	199	100	150
Exclusive Owner IO-Acyc	199	101	150
Exclusive Owner IO	199	102	151
Input only	199	100	193 (empty)
Listen only	199	100	192 (empty)

13.2.2 Parameter data

Content

34170

Configuration Assembly (Instance 199)

34363

The values of the Configuration Assembly are set in RSLogix 5000 via the controller tags of the EtherNet/IP project.

Byte	Content
0	Access rights
1	Process data length
2...13	X01: Port configuration (→ **Mapping: Port configuration** (→ S. 61))
14...25	X02: Port configuration (→ **Mapping: Port configuration** (→ S. 61))
26...37	X03: Port configuration (→ **Mapping: Port configuration** (→ S. 61))
38...49	X04: Port configuration (→ **Mapping: Port configuration** (→ S. 61))

Legend:

- [Access Rights] — Access rights to parameter, process data and events / diagnostics data of the IO-Link master and the connected IO-Link devices — 1 Byte
  - 0x00 EtherNet/IP + IoT
  - 0x01 EtherNet/IP + IoT (ro)
  - 0x02 EtherNet/IP only
  - 0x03 Keep setting (default)
- [Process Data Length] — Length of the process input data and process output data — 1 Byte
  - 0x00 2 Bytes Input / 2 Bytes Output Data
    - Input Assembly: 126 Bytes
    - Output Assembly: 54 Bytes
  - 0x01 4 Bytes Input / 4 Bytes Output Data
    - Input Assembly: 134 Bytes
    - Output Assembly: 62 Bytes
  - 0x02 8 Bytes Input / 8 Bytes Output Data
    - Input Assembly: 150 Bytes
    - Output Assembly: 78 Bytes
  - 0x03 16 Bytes Input / 16 Bytes Output Data
    - Input Assembly: 182 Bytes
    - Output Assembly: 110 Bytes
  - 0x04 32 Bytes Input / 32 Bytes Output Data
    - Input Assembly: 246 Bytes
    - Output Assembly: 174 Bytes

Mapping: Port configuration

34394

Byte
Port Mode
Master Cycle Time
Byte Swap
Validation ID
Vendor ID (MSB)
Vendor ID (LSB)
Device ID (MSB)
Device ID
Device ID (LSB)
reserved
Failsafe Mode -- IO-Link
Failsafe Mode -- pin 4 (DO)

Legend:

▪ [Port Mode]	Operating mode of the IO-Link port	1 byte	0x00	Interface deactivated
			0x01	Operation as digital input (DI)
			0x02	Operation as digital output (D=)
			0x03	Operation as IO-Link port
▪ [Master Cycle Time]	Cycle time of the data transmission between the IO-Link master and the IO-Link device	1 byte	0x00	As fast as possible
			0x01	2 milliseconds
			0x02	4 milliseconds
			0x03	8 milliseconds
			0x04	16 milliseconds
			0x05	32 milliseconds
			0x06	64 milliseconds
			0x07	128 milliseconds
▪ [Byte Swap]	Visualisation of the process data (EtherNet/IP uses Little Endian Format (Intel), IO-Link uses Big Endian Format (Motorola))	1 byte	0x00	Byte swapping for IO-Link process data deactivated
			0x01	Byte swapping for IO-Link process data activated
▪ [Validation ID]	Supported IO-Link standard and behaviour of the IO-Link master when connecting new IO-Link devices to the IO-Link port	1 byte	0x00	No validation
			0x01	V1.0 device
			0x02	V1.1 device
			0x03	V1.1 device with Backup + Restore
			0x04	V1.1 device with Backup

▪ [Vendor ID]	Vendor ID of the manufacturer of the device on the IO-Link port Vendor ID = 0x1234 ▪ Vendor ID (MSB) = 0x12 ▪ Vendor ID (LSB) = 0x34	2 Bytes	pro Byte: 0x00...0xFF	
▪ [Device ID]	Device ID of the device on the IO-Link port Device ID = 0x123456 ▪ Device ID (MSB) = 0x12 ▪ Device ID = 0x34 ▪ Device ID (LSB) = 0x56	3 bytes	pro Byte: 0x00...0xFF	
▪ [Failsafe Mode -- IO-Link]	Fail-safe mode for output data when the EtherNet/IP connection is interrupted	1 byte	0x00	No Failsafe
			0x01	Failsafe Reset Value
			0x02	Failsafe Old Value
			0x03	Failsafe with Pattern
▪ [Failsafe Mode -- pin 4 (DO)]	Fail-safe value for the operating mode "digital output (DO)"	1 byte	0x00	Failsafe Reset Value
			0x01	Failsafe Old Value
			0x02	Failsafe Set Value

13.2.3 Cyclic data

Content

33814

Input assembly (Instance 100): I/O data + acyclic data + diagnosis data

34368

Byte	Content
0...1	Port X01...X04: Digital Input - pin 2 / 4 (DI) (→ **Mapping: digital input data (DI)** (→ S. 67))
2...3	Status information (→ **Mapping: Status information** (→ S. 67))
4...45	Acyclic command area: Response channel (→ **Response channel** (→ S. 76))
46...47	Port X01: PQI (→ **Mapping: PQI** (→ S. 68))
48...63	Port X01: Diagnostic, vendor ID, device ID, events (→ **Mapping: IO-Link port information** (→ S. 69))
64...65	Port X02: PQI (→ **Mapping: PQI** (→ S. 68))
66...81	Port X02: Diagnostic, vendor ID, device ID, results (→ **Mapping: IO-Link port information** (→ S. 69))
82...83	Port X03: PQI (→ **Mapping: PQI** (→ S. 68))
84...99	Port X03: Diagnostic, vendor ID, device ID, events (→ **Mapping: IO-Link port information** (→ S. 69))
100...101	Port X04: PQI (→ **Mapping: PQI** (→ S. 68))
102...117	Port X04: Diagnostic, vendor ID, device ID, events (→ **Mapping: IO-Link port information** (→ S. 69))
118	Port X01: Input data IO-Link (n bytes)
118+n	Port X02: Input data IO-Link (n bytes)
118+2n	Port X03: Input data IO-Link (n bytes)
118+3n	Port X04: Input data IO-Link (n bytes)

Legend:

n = [2,4,8,16,32]; is determined by the parameter [Process_Data_Length] (→ **Configuration Assembly (Instance 199)** (→ S. 60)

Input Assembly (Instance 101): I/O data + acyclic data

34366

Byte	Content
0...1	X01...X04: Digital Input - pin 2 / 4 (DI) (→ **Mapping: digital input data (DI)** (→ S. 67))
2...3	Status information (→ **Mapping: Status information** (→ S. 67))
4...45	Acyclic commando area: Response channel (→ **Response channel** (→ S. 76))
46...47	Port X01: PQI (→ **Mapping: PQI** (→ S. 68))
48...49	Port X02: PQI (→ **Mapping: PQI** (→ S. 68))
50...51	Port X03: PQI (→ **Mapping: PQI** (→ S. 68))
52...53	Port X04: PQI (→ **Mapping: PQI** (→ S. 68))
54	Port X01: Input data IO-Link (n bytes)
54+n	Port X02: Input data IO-Link (n bytes)
54+2n	Port X03: Input data IO-Link (n bytes)
54+3n	Port X04: Input data IO-Link (n bytes)

Legend:

n = [2,4,8,16,32]; is determined by the parameter [Prozess Data Length] (→ **Configuration Assembly (Instance 199)** (→ S. 60))

Input Assembly (Instance 102): I/O data

34373

Byte	Content
0...1	Port X01...X04: Digital input - <IOL_Klmme_Pin> 2 / 4 (DI) (→ **Mapping: digital input data (DI)** (→ S. 67))
2...3	Status information (→ **Mapping: Status information** (→ S. 67))
4...5	Port X01: PQI (→ **Mapping: PQI** (→ S. 68))
6...7	Port X02: PQI (→ **Mapping: PQI** (→ S. 68))
8...9	Port X03: PQI (→ **Mapping: PQI** (→ S. 68))
10...11	Port X04: PQI (→ **Mapping: PQI** (→ S. 68))
12	Port X01: Input data IO-Link (n bytes)
12+n	Port X02: Input data IO-Link (n bytes)
12+2n	Port X03: Input data IO-Link (n bytes)
12+3n	Port X04: Input data IO-Link (n bytes)

Legend:

n = [2,4,8,16,32]; is determined by the parameter [Prozess Data Length] (→ **Configuration Assembly (Instance 199)** (→ S. 60))

Mapping: digital input data (DI)

34405

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	reserved	reserved	reserved	X04: pin 4	X03: pin 4	X02: pin 4	X01: pin 4
reserved	reserved	reserved	reserved	X04: pin 2	X03: pin 2	X02: pin 2	X01: pin 2

Legend:

▪ [pin 4]	Signal level on pin 4 of the IO-Link port	1 bit	0x0	LOW
			0x1	HIGH
▪ [pin 2]	Signal level on pin 2 of the IO-Link port	1 bit	0x0	LOW
			0x1	HIGH

Mapping: Status information

34395

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	reserved	reserved	reserved	X04: Short / OL	X03: Short / OL	X02: Short / OL	X01: Short / OL
reserved	reserved	reserved	reserved	reserved	reserved	Sensor PWR	AUX PWR

Legend:

▪ [Short / OL]	Occurrence of a short circuit or of an overvoltage on the IO-Link port	1 bit	0x0	no error
			0x1	short circuit or overvoltage detected
▪ [Sensor PWR]	Status of the supply voltage US	1 bit	0x0	US not available
			0x1	US available
▪ [AUX PWR]	Status of the supply voltage UA	1 bit	0x0	UA not available
			0x1	UA available

Mapping: PQI

34393

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Diagnosis present	Wrong PD Output Length	Wrong PD Input Length	Wrong Cycle Time	Wrong VID / DID	Invalid Data Bit	Dev Not Conn	IOL Mode
reserved							

Legend:

▪ [IOL Mode]	Operating mode of the IO-Link port	1 bit	0x0	not IO-Link
			0x1	IO-Link
▪ [Dev Not Conn]	Connection between IO-Link Device and IO-Link port	1 bit	0x0	connected
			0x1	not connected
▪ [Invalid Data]	Status of the process input data on the IO-Link port	1 bit	0x0	valid Data
			0x1	invalid Data
▪ [Wrong VID/DID]	Evaluation, whether actual and projected Vendor ID and Device ID match	1 bit	0x0	OK
			0x1	wrong VID and/or DID
▪ [Wrong Cycle Time]	Evaluation, whether actual and projected cycle time match	1 bit	0x0	OK
			0x1	wrong cycle time
▪ [Wrong PD Input Length]	Evaluation, whether actual and projected input process data length match	1 bit	0x0	OK
			0x1	projected length too small
▪ [Wrong PD Output Length]	Evaluation, whether actal and projected output process data length match	1 bit	0x0	OK
			0x1	projected length too small
▪ [Diagnosis present]	Signals a new diagnosis event (Coming Event, Single Shot Event) ▪ Coming Events are removed when if the related Disappearing Event appears ▪ Single Shot Events are removed automatically	1 Bit	0x0	no event
			0x1	New event present

Mapping: IO-Link port information

34413

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VID (LSB)							
VID (MSB)							
DID (LSB)							
DID							
DID (MSB)							
reserved							
Event 1: Mode		Event 1: Type		Event 1: Src	Event 1: Instance		
Event 1: Code (LSB)							
Event 1: Code (MSB)							
Event 2: Mode		Event 2: Type		Event 2: Src	Event 2: Instance		
Event 2: Code (LSB)							
Event 2: Code (MSB)							
Event 3: Mode		Event 3: Type		Event 3: Src	Event 3: Instance		
Event 3: Code (LSB)							
Event 3: Code (MSB)							
reserved							

Legend:

- [VID] Vendor ID of the connected IO-Link device
  VID = 0x1234
  - DID (MSB) = 0x12
  - DID (LSB) = 0x34

  2 bytes — pro Byte: 0x00...0xFF
- [DID] Device ID of the connected IO-Link device
  DID = 0x123456
  - DID (MSB) = 0x12
  - DID = 0x34
  - DID (LSB) = 0x56

  3 bytes — pro Byte: 0x00...0xFF
- [Event m: Mode] Mode: Events mode — 2 bits
  - 0x0 reserved
  - 0x1 Single-shot event
  - 0x2 disappearing event
  - 0x3 appearing event
- [Event m: Type] Type: Event category — 2 bits
  - 0x0 reserved
  - 0x1 Notification
  - 0x2 Warning
  - 0x3 Error
- [Event m: Src] Source: Events source — 1 bit
  - 0x0 IO-Link Device
  - 0x1 IO-Link Master
- [Event m: Instance] Type: Event instance — 3 bits
  - 0x0 Unknown
  - 0x1... 0x3 reserved
  - 0x4 Application

		0x5... 0x7	reserved
▪ [Event m: Code]	Code: Event code; device-dependent Code = 0x1234 ▪ Code (MSB) = 0x12 ▪ Code (LSB) = 0x34	2 bytes	depends on device (→ IODD instructionsof the IO-Link device)

Output assembly (Instance 150): I/O data + acyclic data

34347

Byte	Content
0	Port X01...X04: Digital output pin 4 (DO) (→ **Mapping: Digital output data (DO)** (→ S. 73))
1	reserved
2	reserved
3	reserved
4...45	Acyclic command area: Request channel (→ **Request channel** (→ S. 75))
46	Port X01: Output data IO-Link (n bytes)
46+n	Port X02: Output data IO-Link (n bytes)
46+2n	Port X03: Output data IO-Link (n bytes)
46+3n	Port X04: Output data IO-Link (n bytes)

Legend:

n = [2,4,8,16,32]; is determined by the parameter [Process_Data_Length] (→ **Configuration Assembly (Instance 199)** (→ S. 60)

Output Assembly (Instance 151): I/O data

34346

Byte	Content
0	Port X01...X04: Digital Output - pin 4 (DO) (→ **Mapping: Digital output data (DO)** (→ S. 73))
1	reserved
2	Port X01: Output data IO-Link (n bytes)
2+n	Port X02: Output data IO-Link (n bytes)
2+2n	Port X03: Output data IO-Link (n bytes)
2+3n	Port X04: Output data IO-Link (n bytes)

Legend:

n = [2,4,8,16,32]; is determined by the parameter [Process_Data_Length] (→ **Configuration Assembly (Instance 199)** (→ S. 60)

Mapping: Digital output data (DO)

34415

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
reserved	reserved	reserved	reserved	X04: pin 4	X03: pin 4	X02: pin 4	X01: pin 4

Legend:

▪ [pin 4]	Signal level on pin 4 of the IO-Link port	1 Bit	0x0	LOW
			0x1	HIGH

13.2.4 Acyclic data

Content

33868

Acyclic command channel

34325

In the cyclic process data, command channels for the transmission of acyclic data is available.

Object	Contents	Bytes	Access
Output assembly	Request channel (field bus PLC >>> IO-Link master) → **Request channel** (→ S. 75)	4...45	r/w
Input assembly	Response channel (IO-Link master >>> fieldbus PLC) → **Response channel** (→ S. 76)	4...45	r

Legend:

r = only read access rights
r/w = read and write access rights

Request channel

34398

Byte	Content	
4	Port No. (LSB)	
5	Port No. (MSB)	
6	Index (LSB)	
7	Index (MSB)	
8	Sub-index (LSB)	
9	Sub-index (MSB)	
10	Trigger	Command id
11	Length of the user data (number of bytes)	
12	Data (byte 0)	
13	Data (byte 1)	
..	...	
43	Data (byte 31)	
44	reserved	
45	reserved	

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	8 Bit	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Index]	Index of the IO-Link object Index = 0x1234 ▪ Index (MSB) = 0x12 ▪ Index (LSB) = 0x34	8 Bit	per byte: 0x00...0xFF	
▪ [Subindex]	Subindex of the IO-Link object Subindex = 0x1234 ▪ Subindex (MSB) = 0x12 ▪ Subindex (LSB) = 0x34	8 Bit	per byte: 0x00...0xFF	
▪ [Trigger]	Control of the command execution	1 Bit	0x0 0x1	do not process command execute command
▪ [Command ID]	Command number	7 Bit	0x01 0x02	read write
▪ [Length of user data (number of bytes)]	Number of bytes that contain relevant user data	8 Bit	0x00 ... 0x20	0 bytes 32 bytes
▪ [Data (byte n)]	User data	8 Bit	per byte: 0x00...0xFF	

Response channel

34401

Byte	Contents	
4	Port No. (LSB)	
5	Port No. (MSB)	
6	Index (LSB)	
7	Index (MSB)	
8	Sub-index (LSB)	
9	Sub-index (MSB)	
10	Handshake	Command ID
11	Result	
12	Length of response data (number of bytes)	
13	Data (byte 0) or Error Code	
14	Data (byte 1) or Additional Code	
...	...	
44	Data (byte 31)	
45	reserved	

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	8 bits	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Index]	Index of the IO-Link object Index = 0x1234 ▪ Index (MSB) = 0x12 ▪ Index (LSB) = 0x34	8 bits	per byte: 0x00...0xFF	
▪ [Subindex]	Subindex of the IO-Link object Subindex = 0x1234 ▪ Subindex (MSB) = 0x12 ▪ Subindex (LSB) = 0x34	8 bits	per byte: 0x00...0xFF	
▪ [Handshake]	Validity of the IO-Link response data	1 bit	0x0 0x1	Data invalid Data valid
▪ [Command ID]	Command number	7 bits	0x01 0x02	Read Write
▪ [Result]	Status of the command processing	8 bits	0x00 0x0F 0xFF	OK OK, data read >32 bytes Error occurred
▪ [Length of response data (number of bytes)]	Number of bytes that contain relevant user data	8 bits	0x00 ... 0x20	0 bytes 32 bytes

▪ [Data (byte 0) or Error Code]	User data (byte 0) or error codes	8 bits	User data: 0x00...0xFF Error Code: → **Error codes** (→ S. 78)
▪ [Data (byte 1) or Additional Code]	User data (byte1) or additional error codes	8 bits	User data: 0x00...0xFF Additional Code: → **Additional Codes** (→ S. 78)
▪ [Data (byte n)]	User data (byte n)	8 bits	0x00...0xFF

Error codes

34342

Error code	Description
0x71	Service not available (unknown command has been sent to the IO-Link port)
0x72	Port blocked (another cyclic process accesses the IO-Link port)
0x73	Forbidden (access rights don't allow command processing)
0x74	Invalid data (wrong parameter has been sent in the command)
0x76	Wrong port (wrong port number)
0x77	Wrong port function (wrong port function or wrong parameter has been sent to the device)
0x78	Invalid length (set length is > 0x20)
0x80	Error in the device application; observe additional code (→ **Additional Codes** (→ S. 78))

Additional Codes

54584

Code	Name	Description
0x00	APP_DEV	Device application error - no details
0x11	IDX_NOTAVAIL	Index not available
0x12	SUBIDX_NOTAVAIL	Subindex not available
0x20	SERV_NOTAVAIL	Service temporarily not available
0x21	SERV_NOTAVAIL_LOCCTRL	Service temporarily not available - local control
0x22	SERV_NOTAVAIL_DEVCTRL	Service temporarily not available - device control
0x23	IDX_NOT_WRITEABLE	Access denied
0x30	PAR_VALOUTOFRNG	Parameter value out of range
0x31	PAR_VALGTLIM	Parameter value above limit
0x32	PAR_VALLTLIM	Parameter value below limit
0x33	VAL_LENOVRRUN	Parameter length overrun
0x34	VAL_LENUNDRUN	Parameter length underrun
0x35	FUNC_NOTAVAIL	Function not available
0x36	FUNC_UNAVAILTEMP	Function temporarily not available
0x40	PAR_SETINVALID	Invalid parameter set
0x41	PAR_SETINCONSIST	Inconsistent parameter set
0x82	APP_DEVNOTRDY	Application not ready

Additional Codes are only available, if Error Code = 0x80 (→ **Error codes** (→ S. 78))

Acyclic commands

Content

34331

Command 0x10 – Set mode

34322

The command changes the operating mode of an IO-Link port of the AL1120.

Corresponding parameter: [Port Mode] (→ **Mapping: Port configuration** (→ S. 61))

Command request

34314

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
4	Port No. (LSB)							
5	Port No. (MSB)							
6	reserved							
7	reserved							
8	reserved							
9	reserved							
10	Trigger	0x10						
11	Target Mode							
12...45	reserved							

Legend:

- [Port No.] Number of the IO-Link port
  Port No. = 0x1234
  - Port No. (MSB) = 0x12
  - Port No. (LSB) = 0x34

  16 Bit
  - 0x01 Port X01
  - 0x02 Port X02
  - ...
  - 0x04 Port X04
- [Trigger] Control of the command execution

  1 Bit
  - 0x0 do not process command
  - 0x1 execute command
- [Target Mode] Operating type of the IO-Link port

  8 Bit
  - 0x00 deactivated
  - 0x01 operation as digital input (DI)
  - 0x02 operation as digital output (DO)
  - 0x03 operation as IO-Link intervals

Command response

34316

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
4	Port No. (LSB)							
5	Port No. (MSB)							
6	reserved							
7	reserved							
8	reserved							
9	reserved							
10	Handshake	0x10						
11	Result							
12	Target Mode							
13...45	reserved							

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	2 Byte	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Handshake]	Status of the execution of the command	1 Bit	0x0 0x1	command is executed execution of the command was successful
▪ [Result]	Error indication	1 Byte	0x00 0x01	no error error occured
▪ [Target Mode]	Operating type of the IO-Link port	1 Byte	0x00 0x01 0x02 0x03	deactivated operation as digital input (DI) operation as digital output (DO) operation as IO-Link intervals

Command 0x20 – Set validation ID / data storage

34321

The command sets the behaviour of the IO-Link master when connecting a new IO-Link device to an IO-Linkport of the device.

Corresponding parameter: [Validation ID] (→ **Mapping: Port configuration** (→ S. 61))

Command request

34315

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
4	Port No. (LSB)							
5	Port No. (MSB)							
6	reserved							
7	reserved							
8	reserved							
9	reserved							
10	Trigger	0x20						
11	Validation ID							
12...42	reserved							

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	2 byte	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Trigger]	Control command execution	1 Bit	0x0 0x1	do not process command execute command
▪ [Validation ID]	Behaviour of the IO-Link master when connecting an IO-Link device to the IO-Link port	1 byte	0x0 0x1 0x2 0x3 0x4	No check Type compatible V1.0 Device Type compatible V1.1 Device Type compatible V1.1 Device with Backup + Restore Type compatible V1.1 Device with Restore

Command response

34362

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
4	Port No. (LSB)							
5	Port No. (MSB)							
6	reserved							
7	reserved							
8	reserved							
9	reserved							
10	Handshake	0x20						
11	Result							
12	Validation ID							
13..45	reserved							

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	2 byte	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Handshake]	Status of the execution of the command	1 bit	0x0 0x1	command is executed execution of the command was successful
▪ [Result]	Error indication	1 byte	0x00 0x01	no error errors occurred
▪ [Validation ID]	Behaviour of the IO-Link master when connecting an IO-Link device to the IO-Link port	1 byte	0x0 0x1 0x2 0x3 0x4	No check Type compatible V1.0 Device Type compatible V1.1 Device Type compatible V1.1 Device with Backup + Restore Type compatible V1.1 Device with Restore

Command 0x30 – Set fail-safe data pattern

34379

The command sets the behaviour of the outputs when the EtherNet/IP connection and the corresponding fail-safe values are interrupted.

Corresponding parameter: [Fail-safe Mode] (→ **Mapping: Port configuration** (→ S. 61)
The number of the required fail-safe values results from the size of the output data (→ **Configuration Assembly (Instance 199)** (→ S. 60)).

Command request

34317

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
4	Port No. (LSB)							
5	Port No. (MSB)							
6	reserved							
7	reserved							
8	reserved							
9	reserved							
10	Trigger	0x30						
11	Fail-safe mode							
12	Byte Length N							
13	Fail-safe data (byte 0)							
...	...							
44	Fail-safe data (byte 31)							
45	reserved							

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	16 Bit	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Trigger]	Control command execution	1 Bit	0x0 0x1	do not process command execute command
▪ [Fail-safe Mode]	Behaviour of the outputs when the EtherNet/IP connection is interrupted and setting of the corresponding fail-safe values	8 Bit	0x00 0x01 0x02 0x03	No Fail-safe Fail-safe Reset Value Fail-safe Old Value Fail-safe with Pattern
▪ [Byte Length N]	Number of the bytes that contain fail-safe values	8 Bit	0x00 ... 0x20	0 Bytes 32 Bytes
▪ [Fail-safe Data (Byte n)]	Fail-Safe value n (n = 0...31)	8 Bit	per byte: 0x00...0xFF	

Command response

34361

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
4	Port No. (LSB)							
5	Port No. (MSB)							
6	reserved							
7	reserved							
8	reserved							
9	reserved							
10	Handshake	0x30						
11	Result							
12	Fail-safe mode							
13...45	reserved							

Legend:

▪ [Port No.]	Number of the IO-Link port Port No. = 0x1234 ▪ Port No. (MSB) = 0x12 ▪ Port No. (LSB) = 0x34	16 Bit	0x01 0x02 ... 0x04	Port X01 Port X02 Port X04
▪ [Handshake]	Status of the execution of the command	1 Bit	0x0 0x1	command is executed execution of the command was successful
▪ [Result]	Error indication	1 Bit	0x0 0x1	no error error occured
▪ [Fail-safe Mode]	Behaviour of the outputs when the EtherNet/IP connection is interrupted	8 Bit	0x00 0x01 0x02 0x03	No Fail-safe Fail-safe Reset Value Fail-safe Old Value Fail-safe with Pattern

Field bus objects

Content

34352

CIP class services

34335

The device supports the following class and instance services:

Class code		Service	Description
dec	hex		
01	01	Get Attribute All	Read all attribute values of the class or instance
02	02	Set Attribute All	Change all attribute values of the class or instance
05	05	Reset	Reset
09	09	Delete	Delete
14	0E	Get Attribute Single	Read single attribute value of the class or instance
16	10	Set Attribute Single	Change single attribute value of the class or instance
75	4B	Read ISDU	Read ISDU
76	4C	Write ISDU	Write ISDU
77	4D	Write Failsafe Pattern	Write failsafe pattern
78	4E	Forward Close	Close connection
84	54	Forward Open	Open new connection

CIP object classes

34334

The device supports the following CIP object classes:

Class code		Object type	Reference
dec	hex		
01	01	Identity Object	→ **Identity Object (object class: 0x01)** (→ S. 88)
02	02	Message Router Object	→ **Message Router Object (object class: 0x02)** (→ S. 90)
04	04	Assembly Object	→ **Assembly Object (object class: 0x04)** (→ S. 91)
06	06	Connection Manager Object	→ **Connection Manager Object (object class: 0x06)** (→ S. 92)
71	47	Device Level Ring Object	→ **Device Level Ring Object (object class: 0x47)** (→ S. 93)
72	48	Quality of Service	→ **Quality of Service (object class: 0x48)** (→ S. 94)
128	80	IO-Link Requests	→ **IO-Link requests (object class: 0x80)** (→ S. 95)
245	F5	TCP/IP Object	→ **TCP/IP object (object class: 0xF5)** (→ S. 105)
246	F6	Ethernet Link Object	→ **Ethernet Link Object (object class: 0xF6)** (→ S. 107)

Identity Object (object class: 0x01)

34340

The Identity Object contains the general information about the device.

Class attributes

34310

Attr. ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	1
2	Get	Max instance	UINT	Max. number of instances of the object	1
6	Get	Maximum ID Number Class Attributes	UINT	ID of the last class attribute	7
7	Get	Maximum ID Number Instance Attributes	UINT	ID of the last instance attribute	9

Instance attributes

34339

Attr. ID	Access	Name	Data type	Description	Preset
1	Get	Vendor ID	UINT	Manufacturer ID	322
2	Get	Device type	UINT	Type of unit	12
3	Get	Product code	UINT	Identification of a particular product of a vendor	1120
4	Get	Revision	STRUCT	Revision of the article that is represented by the Identity Object	1.1
		▪ Major revision	USINT	Main revision (1...127)	1
		▪ Minor revision	USINT	Side revision (3 digits, if necessary with zeros in the beginning)	1
5	Get	Status	WORD	Status of the device	
6	Get	Serial number	UDINT	Serial number of the device	
7	Get	Product Name	SHORT STRING	Readable device designation (max. 32 ASCII characters)	IO-Link Master SL EIP 4P IP67
8	Get	State	USINT	Current status of the device (according to status transition diagram)	
				0 Nonexistent	
				1 Device Self Testing	
				2 Standby	
				3 Operational	
				4 Major Recoverable Fault	
				5 Major Unrecoverable Fault	
				6...254 Reserved	
				255 Default for Get_Attributes_All service	
9	Get	Configuration Consistency Value	UINT	The content shows the configuration of the device	0

Supported services

34377

Service code		Name	Class	Attribute	Description
dec	hex				
01	01	Get_Attribute_All	yes	yes	Read all attributes
05	05	Reset	yes	yes	Reset
14	0E	Get_Attribute_Single	yes	yes	Read single attribute
16	10	Set_Attribute_Single	yes	yes	Change single attribute

If an Identity Object receives a reset request, it carries out the following actions:

- It checks if it supports the requested reset type.
- It responds to the request.
- It tries to execute the requested reset type.

Supported reset types:

- 0 Reboot the device (obligatory for all EtherNet/IP devices).
- 1 Restore factory settings and reboot the device.

Message Router Object (object class: 0x02)

34390

The Message Router Object provides an access with which an EtherNet/IP client can address a service to any object class or instance in the physical device.

Class attributes

34320

Attr. ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	1
2	Get	Max instance	UINT	Max. number of instances of the object	1
3	Get	Number of Instances	UINT	Number of instances	1
6	Get	Maximum ID Number Class Attributes	UINT	ID of the last class attribute	7
7	Get	Maximum ID Number Instance Attributes	UINT	ID of the last instance attribute	0

Instance attributes

34402

The object has no instance attributes.

Supported services

34374

Service code		Name	Class	Attribute	Description
dec	hex				
14	0E	Get_Attribute_Single	yes	no	Read single attribute value

Assembly Object (object class: 0x04)

34332

The Assembly Object combines attributes of several objects to allow data to be sent to or received from each object via one connection.

Class attributes

34309

Attr. ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	2
2	Get	Max instance	UINT	Max. number of instances of the object	0x00C7
3	Get	Number of Instances	UINT	Number of instances	3
6	Get	Maximum ID Number Class Attributes	UINT	ID of the last class attribute	7
7	Get	Maximum ID Number Instance Attributes	UINT	ID of the last instance attribute	4

Instance attributes

34403

Attr. ID	Access	Name	Data type	Description	Preset
100	Get	Input assembly	STRUCT	Cyclic input data (→ **Input assembly (Instance 100): I/O data + acyclic data + diagnosis data** (→ S. 64))	--
101	Get	Input assembly	STRUCT	Cyclic input data (→ **Input Assembly (Instance 101): I/O data + acyclic data** (→ S. 65))	--
102	Get	Input assembly	STRUCT	Cyclic input data (→ **Input Assembly (Instance 102): I/O data** (→ S. 66))	--
150	Get, Set	Output assembly	STRUCT	Cyclic output data (→ **Output assembly (Instance 150): I/O data + acyclic data** (→ S. 71))	--
151	Get, Set	Output assembly	STRUCT	Cyclic output data (→ **Output Assembly (Instance 151): I/O data** (→ S. 72))	--
199	Get, Set	Configuration assembly	STRUCT	Configuration data (→ **Configuration Assembly (Instance 199)** (→ S. 60))	--

Supported services

34376

Service code		Name	Class	Attribute	Description
dec	hex				
14	0E	Get_Attribute_Single	yes	yes	Read attribute value
16	10	Set_Attribute_Single	no	yes	Change attribute value

Connection Manager Object (object class: 0x06)

34367

The Connection Manager Object structures and manages the internal resources that are used for the connection.

Class attributes

34319

Attr ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	1
2	Get	Max instance	UINT	Max. number of instances of the object	1
3	Get	Number of Instances	UINT	Number of instances	3
6	Get	Maximum ID Number Class Attributes	UINT	ID of the last class attribute	7
7	Get	Maximum ID Number Instance Attributes	UINT	ID of the last instance attribute	0

Instance attributes

34402

The object has no instance attributes.

Supported services

34375

Service code		Name	Class	Attribute	Description
dec	hex				
14	0E	Get_Attribute_Single	yes	yes	Read single attribute
16	10	Set_Attribute_Single	no	yes	Change single attribute
78	4E	Forward_Close	yes	no	Close connection
84	54	Forward_Open	yes	no	Open new connection

Device Level Ring Object (object class: 0x47)

34345

The Device Level Ring (DLR) Object represents the interface for configuration and status information.

Class attributes

34313

Attr ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	3
2	Get	Max instance	UINT	Max. number of instances of the object	1
6	Get	Maximum ID Number Class Attributes	UINT	ID of the last class attribute	7
7	Get	Maximum ID Number Instance Attributes	UINT	ID of the last instance attribute	12

Instance attributes

34327

Attr. ID	Access	Name	Data type	Description		Preset
1	Get	Network Topology	USINT	current network topology		0
2	Get	Network status	USINT	current network status		0
10	Get	Active Supervisor	STRUCT of	Identification of the supervisor		0
			▪ UDINT	IP address of the supervisor		
			▪ ARRAY of 6 USINTs	MAC address of the supervisor		
12	Get	Capability Flags	DWORD	DLR functions of the device		0x82
				Bit 0	Announced-based ring node	0
				Bit 1	Beacon-based ring node	1
				Bit 2...4	reserved	--
				Bit 5	Supervisor capable	0
				Bit 6	Redundant Gateway capable	0
				Bit 7	Flush_Table frame capable	1
				Bit 8..31	reserved	--

I

Supported services

34409

Service code		Name	Class	Attribute	Description
dec	hex				
1	01	Get_Attribute_All	no	yes	Read all attribute values
14	0E	Get_Attribute_Single	yes	yes	Read single attribute value

Quality of Service (object class: 0x48)

34371

Quality of Service (QoS) enables prioritising of Ethernet frames. The priorities of the Ethernet frames can be influenced with the attributes "Differentiate Service Code Points" (DSCP) or "802.1Q Tag".

Class attributes

34307

Attr ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	3
2	Get	Max instance	UINT	Max. number of instances of the object	1
6	Get	Maximum ID Number Class Attributes	UINT	ID of the last class attribute	7
7	Get	Maximum ID Number Instance Attributes	UINT	ID of the last instance attribute	8

Instance attributes

34328

Attr ID	Access	Name	Data type	Description	Value
1	Get	802.1Q tagRevision	USINT	Current network topology	0
2	Get, Set	DSCP PTP Event	USINT	DSCP value for PTP event frames	59
3	Get, Set	DSCP PTP general	USINT	DSCP value for PTP general frames	47
4	Get, Set	DSCP PTP Urgent	USINT	DSCP value for implicit messages with "urgent" priority	55
5	Get, Set	DSCP Scheduled	USINT	DSCP value for implicit messages with "scheduled" priority	47
6	Get, Set	DSCP High	USINT	DSCP value for implicit messages with "high" priority	43
7	Get, Set	DSCP Low	USINT	DSCP value for implicit messages with "low" priority	31
8	Get, Set	DSCP explicit	USINT	DSCP value for explicit messages with "scheduled" priority	27

Supported services

34406

Service code		Name	Class	Attribute	Description
dec	hex				
01	01	Get_Attribute_All	yes	yes	Read all attribute values
14	0E	Get_Attribute_Single	no	yes	Read single attribute value

IO-Link requests (object class: 0x80)

34412

The manufacturer-specific object "IO-Link Requests" enables read and write access to the IO-Link objects of an IO-Link device connected to a AL1120 via ISDU (Index Service Data Unit). The object projects the mechanisms of the CIP addressing on the IO-Link protocol.

Class attributes

34308

Attr ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	4
2	Get	Max instance	UINT	Max. number of instances of the object	2
6	Get	Maximum ID Number Class Attributes	UINT	Number of instances of the object	8

Instance attributes

34399

The required IO-Link port of the device is addressed via the instance attribute.

Supported services

34378

Service code		Name	Class	Attribute	Description
dec	hex				
75	4B	→ **Read_ISDU** (→ S. 96)	no	yes	Read ISDU
76	4C	→ **Write_ISDU** (→ S. 99)	no	yes	Read ISDU
77	4D	→ **Write Failsafe Pattern** (→ S. 102)	no	yes	Write failsafe values of IO-Link port

Read_ISDU

34323

With Read_ISDU, parameters of a connected IO-Link device can be read.

Request

34337

CIP Attribute determines the IO-Link port to which the IO-Link device is connected. The area CIP User Specific Service Data contains the IO-Link index and the IO-Link sub-index of the IO-Link object whose value is to be read:

CIP format	Data type	MSG Config	IO-Link mapping
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x01...0x04	Port number
CIP Service code ID	USINT	0x4B	Request "Read_ISDU"
CIP User specific service data	UINT	0x0000...0xFFFF	IO-Link ISDU object index
	USINT	0x00...0xFF	IO-Link ISDU object sub-index

Response

34326

- **Positive response**

If the service has been executed successfully (CIP Error Code = 0), the read data are returned bit by bit (CIP User Specific Service Data). The answer has the following format:

CIP format	Data type	MSG Config	IO-Link mapping
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4C	Response "Read_ISDU"
CIP Error Code	USINT	0x00	--
CIP Extended Error Code	USINT	0x00	--
CIP User Specific Service Data	USINT	0x00...0xFF	Data (byte 0)
	USINT	0x00...0xFF	Data (byte 1)
	...		...
	USINT	0x00...0xFF	Data (byte n)

The read data is in the IO-Link format. If necessary, the user needs to adapt the byte arrangement of the read data to the CIP format.

- **Negative response**

If an error occurs while executing the service (CIP Error Code <> 0), an extended error code is transmitted. If the CIP Error Code = 0x1E, then the CIP Extended Error Code = 0x00 and the CIP User Specific Service Data area contains the IO-Link Error Code as well as IO-Link Additional Code. The answer has the following format:

CIP format	Data type	MSG Config	IO-Link mapping
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4B	Response "Read_ISDU"
CIP Error Code	USINT	<> 0x00	Error code: see table below
CIP Extended Error Code	USINT	0x00	Extended error code
CIP User Specific Service Data	USINT	<> 0x00	IO-Link Error Code: → **Error codes** (→ S. 78) (only if CIP Error Code = 0x1E)
	USINT	<> 0x00	IO-Link Additional Code: → **Additional Codes** (→ S. 78) (only if CIP Error Code = 0x1E)

CIP Error Code:

Code	Description
0x02	Resource not available: The IO-Link port is busy processing another acyclic service.
0x05	Invalid class ID or instance ID
0x08	Wrong service ID: only service code 0x4B or 0x4C is permitted
0x09	Wrong attribute ID: wrong port number
0x20	Invalid parameter value (e.g. invalid length)
0x1E	Embedded service, error: Error occurred during an IO-Link service. Byte 0 and byte 1 of the User Specific Service Data contain the IO-Link error code and an additional code that are returned by the IO-Link master.

Example: reading the parameter value of anIO-Link device

34350

Task: reading the value of the parameter X of an IO-Link device

- IO-Link device at the port: 0x02
- Parameter X in the object directory of an IO-Link device: Index: 90, sub-index 3

From this, the following results for the configuration of the EtherNet/IP command Message (MSG):

CIP format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x02	Port number
CIP Service Code ID	USINT	0x4B	Request "ISDU_Read"
CIP User Specific Service Data	UINT	0x005A	IO-Link ISDU object index
	USINT	0x03	IO-Link ISDU object sub-index

After successful execution of the request, the response area has the following content:

CIP format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	Object class "IO-Link requests"
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x02	Port number
CIP Service Code ID	USINT	0x4B	Response "ISDU_Read"
CIP Error Code	USINT	0x00	Request processed successfully
CIP Extended Error Code	USINT	0x00	--
CIP User Specific Service Data	USINT	e.g. 0x12	Parameter value that has been read (byte 0)
	USINT	e.g. 0x34	Parameter value that has been read (byte 1)

If an error occurs while the request is executed, the response area has the following content:

CIP format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	Object class "IO-Link requests"
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x02	Port number
CIP Service code ID	USINT	0x4B	Response "ISDU_Read"
CIP Error code	USINT	0x1E	Error code: Embedded service error
CIP Extended error code	USINT	0x00	--
CIP User specific service data	USINT	e.g. 0x80	IO-Link Error Code: Error in device application
	USINT	e.g. 0x20	IO-Link Additional Code: Service temporarily unavailable

Write_ISDU

34385

With Write_ISDU, the parameters of a connected IO-Link device can be changed.

Request

34387

CIP Attribute determines the IO-Link port to which the IO-Link device is connected. The area CIP User Specific Service Data contains the IO-Link index, the IO-Link sub-index of the IO-Link object whose value is to be changed. It is followed, bit by bit, by the value that is to be assigned to the parameter.

CIP format	Data type	MSG Config	IO-Link mapping
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x1	IO-Link master
CIP Attribute	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4C	Request "Write_ISDU"
CIP User Specific Service Data	UINT	0x0000...0xFFFF	IO-Link ISDU object index
	USINT	0x00...0xFF	IO-Link ISDU object sub-index
	USINT	0x00...0xFF	IO-Link ISDU data (byte 0)
	USINT	0x00...0xFF	IO-Link ISDU data (byte 1)

Response

34384

- **Positive response**

If the service has been executed successfully (CIP Error Code = 0), the area CIP User Specific Service Data stays empty The answer has the following format:

CIP format	Data type	MSG Config	IO-Link mapping
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4C	Response "Write_ISDU"
CIP Error Code	USINT	0x00	--
CIP Extended Error Code	USINT	0x00	--

- **Negative response**

If an error occurs while executing the service (CIP Error Code <> 0), an extended error code is transmitted. If the CIP Error Code = 0x1E, then the CIP Extended Error Code = 0x00 and the CIP User Specific Service Data area contains the IO-Link Error Code as well as IO-Link Additional Code. The answer has the following format:

CIP format	Data type	MSG Config	IO-Link mapping
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4C	Response "Write_ISDU"
CIP Error Code	USINT	<> 0x00	Error code. see table below
CIP Extended Error Code	USINT	0x00	Extended error code
CIP User Specific Service Data	USINT	<> 0x00	IO-Link Error Code: → **Error codes** (→ S. 78) (only if CIP Error Code = 0x1E)
	USINT	<> 0x00	IO-Link Additional Code: → **Additional Codes** (→ S. 78) (only if CIP Error Code = 0x1E)

CIP Error Code:

Code	description
0x02	Resource not available: The IO-Link port is busy processing another acyclic service.
0x05	Invalid class ID or instance ID
0x08	Wrong service ID: only service code 0x4B or 0x4C is permitted
0x09	Wrong attribute ID: wrong port number
0x20	Invalid parameter value (e.g. invalid length)
0x1E	Embedded service, error: Error occurred during an IO-Link service. Byte 0 and byte 1 of the User Specific Service Data contain the IO-Link error code and an additional code that are returned by the IO-Link master (see below).

Example: changing the parameter value of an IO-Link device

34355

Task: changing the parameter X of an IO-Link device

- IO-Link device at the port: 0x03
- Parameter X in the object directory of an IO-Link device: Index: 91, sub-index 5
- new parameter value: 0xABCD

From this, the following results for the configuration of the EtherNet/IP command Message (MSG):

CIP format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x03	Port number
CIP Service code ID	USINT	0x4C	Service "Write_ISDU"
CIP User specific service data	UINT	0x005B	IO-Link ISDU object index
	USINT	0x05	IO-Link ISDU object sub-index
	USINT	0xAB	New parameter value (MSB)
	USINT	0xCD	New parameter value (LSB)

After successful execution of the request, the response area has the following content:

CIP format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	Object class "IO-Link Requests"
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x03	Port number
CIP Service code ID	USINT	0x4B	Service "Write_ISDU"
CIP Error code	USINT	0x00	Request processed successfully
CIP Extended error code	USINT	0x00	--

If an error occurs while the request is executed, the response area has the following content:

CIP format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	Object class "IO-Link Requests"
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attributes	USINT	0x03	Port number
CIP Service code ID	USINT	0x4B	Service "Write_ISDU"
CIP Error code	USINT	0x1E	Error code: Embedded Service Error
CIP Extended error code	USINT	0x00	--
CIP User specific service data	USINT	0x80	IO-Link Error Code: Error in device application
	USINT	0x23	IO-Link Additional Code: Access denied

Write Failsafe Pattern

54597

By using Write Failsafe Pattern the fail-safe value of a IO-Link port can be written.

Request

54694

CIP Attribute determines the IO-Link port. The area CIP User Specific Service Data includes the fail-safe mode and the fail-safe value (Failsafe Pattern).

CIP Format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4D	Request "Write Failsafe Pattern"
CIP User Specific Service Data	USINT	0x00 = No Fail-safe 0x01 = Fail-safe Reset Value 0x02 = Fail-safe Old Value 0x03 = Fail-safe with Pattern	Failsafe Mode
	USINT	0x00...0xFF	Failsafe Pattern (MSB)
	USINT	0x00...0xFF	Failsafe Pattern (LSB)

Response

54695

- **Positive response**

If the service was executed successfully (CIP Error Code = 0), the area "User Specific Data" will remain empty. The response has the following format:

CIP Format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4D	Response "Write Failsafe Pattern"
CIP Error Code	USINT	0x00	--
CIP Extended Error Code	USINT	0x00	--

- **Negative response**

If an error occurs while executing the service (CIP Error Code <> 0), an extended error code is transmitted (CIP Extended Error Code). The answer has the following format:

CIP-Format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x01...0x04	Port number
CIP Service Code ID	USINT	0x4D	Response "Write Failsafe Pattern"
CIP Error Code	USINT	<> 0x00	Error code: see below
CIP Extended Error Code	USINT	<> 0x00	Extended error code

CIP Error Code:

Code	Description
0x02	Resource not available: The IO-Link port is busy processing another acyclic service.
0x05	Invalid class ID or instance ID
0x08	Wrong service ID: only service 0x4B, 0x4C or 0x4D is permitted
0x09	Wrong attribute ID: wrong port number
0x20	Invalid parameter value (e.g. invalid length)
0x1E	Embedded service, error: Error occurred during an IO-Link service. Byte 0 and byte 1 of the User Specific Service Data contain the IO-Link error code and an additional code that are returned by the IO-Link master (see below).
0x0F	Insufficient access rights

Example: Write fail-safe value

54696

Task: Write fail-safe mode for IO-Link port X02 to "Fail-safe with pattern" and fail-safe value to 0x1234

- IO-Link device in the port: 0x02
- Fail-safe mode: 0x03
- Fail-safe value: 0x1234

From this, the following results for the configuration of the EtherNet/IP command message (MSG):

CIP Format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x02	Port number
CIP Service Code ID	USINT	0x4D	Request "Write Failsafe Pattern"
CIP User Specific Service Data	USINT	0x03	"Fail-safe with Pattern" mode
	USINT	0x12	Failsafe Pattern (MSB)
	USINT	0x34	Failsafe Pattern (LSB)

After successful execution of the request, the response area has the following content:

CIP-Format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x02	Port number
CIP Service Code ID	USINT	0x4D	Response "Write Failsafe Pattern"
CIP Error Code	USINT	0x00	Request processed successfully
CIP Exended Error Code	USINT	0x00	--

If an error occurs while the request is executed, the response area will have the following content:

CIP-Format	Data type	MSG Config	Description
CIP Class ID	UINT	0x80	IO-Link acyclic access
CIP Instance ID	UINT	0x01	IO-Link master
CIP Attribute	USINT	0x02	Port number
CIP Service Code ID	USINT	0x4D	Response "Write Failsafe Pattern"
CIP Error Code	USINT	e. g. 0x0F	Error code: Insufficient access rights
CIP Exended Error Code	USINT	0x00	no additional information

TCP/IP object (object class: 0xF5)

34388

TCP/IP Interface Object enables the configuration of the physical network interface of the device.

Class attributes

34311

Attr ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	4
2	Get	Max instance	UINT	Max. number of instances of the object	1

Instance attributes

34330

Attr. ID	Access	Name	Data type	Description	Preset
1	Get	Status	DWORD	Status of the TCP/IP interface	
				Bit 0...3: Configuration status of the interface	
				Bit 4: Mcast pending (always 0)	
				Bit 5: Interface configuration pending	
				Bit 6: ACD Status	
				Bit 7: ACD Fault	
				Bit 8...31: reserved	
2	Get	Configuration Capability	DWORD	Functions of the interface (flags)	0x95 (BOOTP,DHCP Client,TCP/IP configurable, ACD capable)
				Bit 0: BOOTP Client	
				Bit 1: reserved	
				Bit 2: DHCP Client	
				Bit 3: reserved	
				Bit 4: TCP/IP configurable via EtherNet/IP	
				Bit 5: reserved	
				Bit 6: reserved	
				Bit 7: ACD Capable	
				Bit 8...31: reserved	
3	Get, Set	Configuration Control	DWORD	Interface control (control flags):	0
				Bit 0...3: Start-up configuration	
				0: Static IP configuration	
				1: Configuration via BOOTP	
				2: Configuration via DHCP	
				Bit 4: reserved	
				Bit 5...31: reserved	
4	Get	Physical Link Object path	STRUCT:	Logical path to the physical communication interface: the Ethernet Link object	
		▪ Path Size	▪ UINT	Length (in Little Endian Format as WORD)	02 00

Attr. ID	Access	Name	Data type	Description	Preset
		▪ Path	▪ Padded EPATH	Path	20 F6 24 01
				Class ID = 0xF6 Ethernet Link Object	
				Instance ID = 1	
5	Get, Set	Interface Configuration	STRUCT:	TCP/IP configuration	
		▪ IP Address	▪ UDINT	IP adress	192.168.1.250
		▪ Network mask	▪ UDINT	Subnet mask	255.255.255.0
		▪ Gateway address	▪ UDINT	Default gateway address	0.0.0.0
		▪ Name Server	▪ UDINT	1. Name Server	0.0.0.0
		▪ Name Server 2	▪ UDINT	2. Name Server	0.0.0.0
		▪ Domain Name	▪ STRING	Default domain name	0
6	Get, Set	Host name	STRING	Host name	0
				0 no name configured	
8	Get	TTL value		TTL value	1
9	Get	Mcast Config			0
10	Get, Set	SelectAcd	BOOL	activate ACD	1
				0 deactivate	
				1 activate	
11	Get, Set	Last Conflict Detected	STRUCT:	Structure with information via the latest detected conflict	0
			▪ USINT	Condition of the ACD activity with the latest detected conflict	
				0 Noconflictdetetcted	
				1 Probelpv4Address	
				2 OngoingDetection	
				3 SemiActiveProbe	
			▪ ARRAY of 6 USINT	MAC address	
			▪ ARRAY of 28 USINT	Copy of the data of the ARP PDU in which the conflict was detected	
13	Get, Set	Encapsulation Inactivity Timeout	UINT	Inactivity before the TCP connection is deactivated (in seconds)	120

Supported services

34416

Service code		Name	Class	Attribute	Description
dec	hex				
01	01	Get_Attribute_All	no	yes	Read all attributes
14	0E	Get_Attribute_Single	yes	yes	Read single attribute
16	10	Set_Attribute_Single	no	yes	Change single attribute

Ethernet Link Object (object class: 0xF6)

34354

The Ethernet Link Object contains status information of the Ethernet interface.

Class attributes

34312

Attr ID	Access	Name	Data type	Description	Value
1	Get	Revision	UINT	Revision of the object	4
2	Get	Max Instance	UINT	Max. number of instances of the object	2
3	Get	Number of Instances	UINT	Number of instances of the object	2

Instance attributes

34333

Attr. ID	Access	Name	Data type	Description		Preset
1	Get	Interface Speed	UDINT	Current data rate (in bytes/s) 10 Mbps,100 Mbps.		100
2	Get	Interface Status Flags	DWORD	Status flag of the interface		0x20
				Bit 0	Link status	
				Bit 1	Half/full duplex	
				Bit 2...4	Auto negotiation status	
				Bit 5	Manual setting requires reset	
				Bit 6	Local Hardware Fault	
				Bit 7...31	reserved	
3	Get	Physical Address	ARRAY of 6 USINTS	MAC address		
4	Get	Interface Counters	STRUCT of 11 UDINTs	Interface-specific counter		
5	Get	Media counters	STRUCT of 12 UDINTs	Medium-specific counter		
6	Get, Set	Interface control	STRUCT of	Control bits: Bit 0: Auto negotiate Bit 1: Forced Duplex Mode (full 1, half 0)		0
			▪ WORD	Control bits of the interface		
				Bit 0	0 = auto-negotiation active	
					1 = auto-negotiation inactive	
				Bit 1	0 = Half duplex	
					1 = Full duplex	
				Bit 2..15	reserved	
			▪ UINT	Data rate of the interface		
				10	10 Mbps	
				100	100 Mpbs	
7	Get	Interface Type	USINT	Physical interface type		2
				0	unknown	
				1	Internal interface	
				2	Twisted pair	

Attr. ID	Access	Name	Data type	Description		Preset
				3	Optical fibre	
				4...255	reserved	
8	Get	Interface state	USINT	Current status of the interface		0
				0	unknown	
				1	active; ready for transmission and reception	
				2	not active	
				3	Test mode	
				4...255	reserved	
9	Get	Admin State	USINT	Control of the access to the interface		1
				0	reserved	
				1	Activate interface	
				2	Deactivate interface	
				3...255	reserved	
10	Get	Interface label	SHORT_ STRING	Designation of the interface		"X21" (instance 1) "X22" (instance 2)
11	Get	Interface capability	STRUCT of	Capabilities of the interface		
			▪ DWORD	Transmission rate		
				10	10 Mbps	
				100	100 Mbps	
			▪ DWORD	Duplex mode		
				HD	Half duplex	
				FD	Full duplex	
300	Get, Set	MDIX	???	MDIX configuration		3
				0		
				1	MDI	
				2	MDIX	
				3	autoMDI	
				4...255	reserved	

Supported services

34414

Service code		Name	Class	Attribute	Description
dec	hex				
01	01	Get_Attribute_All	no	yes	Read all attribute values
14	0E	Get_Attribute_Single	yes	yes	Read single attribute value
16	10	Set_Attribute_Single	no	yes	Change single attribute value

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