	Technical data	
	General specifications	
	Sensing range	70 1000 mm
	Adjustment range	90 1000 mm
	Dead band	0 70 mm
	Standard target plate	100 mm x 100 mm
	Transducer frequency Response delay	approx. 255 kHz approx. 125 ms
	Indicators/operating means	approx. 125 ms
	LED yellow	solid yellow: object in the evaluation range yellow, flashing: program function, object detected
	LED red	solid red: Error red, flashing: program function, object not detected
	Electrical specifications	rea, hashing. program function, object not detected
	Operating voltage U <sub>B</sub>	10 30 V DC , ripple 10 % <sub>SS</sub>
	No-load supply current I0	≤ 45 mA
	Input/Output	
	Synchronization	bi-directional 0 level -U <sub>B</sub> +1 V 1 level: +4 V+U <sub>B</sub> input impedance: > 12 KOhm synchronization pulse: $\geq$ 100 µs, synchronization interpulse period: $\geq$ 2 ms
Model Number	Synchronization frequency	
UB1000-18GM75A-I-V15	Common mode operation	$\leq$ 40 Hz
	Multiplex operation Input	≤ 40/n
Single head system Features	Input type	1 program input lower evaluation limit A1: -U <sub>B</sub> +1 V, upper evaluation limit
		A2: +4 V +U <sub>B</sub> input impedance: > 4.7 k $\Omega$ , pulse duration: $\geq$ 1 s
<ul> <li>Analog output 4 mA 20 mA</li> </ul>	Output	be been a b
<ul> <li>Measuring window adjustable</li> </ul>	Output type	1 analog output 4 20 mA
Selectable sound lobe width	Resolution	0.35 mm
	Deviation of the characteristic curve	± 1 % of full-scale value
<ul> <li>Program input</li> </ul>	Repeat accuracy Load impedance	± 0.1 % of full-scale value 0 300 Ohm
<ul> <li>Synchronization options</li> </ul>	Temperature influence	± 1.5 % of full-scale value
	Ambient conditions	
<ul> <li>Deactivation option</li> </ul>	Ambient temperature	-25 70 °C (-13 158 °F)
<ul> <li>Temperature compensation</li> </ul>	Storage temperature	-40 85 °C (-40 185 °F)
	Mechanical specifications Connection type	Connector plug M12 x 1 , 5-pin
Very small unusable area	Degree of protection Material	IP67
Diagrams	Housing	brass, nickel-plated
	Transducer	epoxy resin/hollow glass sphere mixture; polyurethane foam
Characteristic response curve	Mass Compliance with standards and directives	60 g
Distance Y [mm]	Standard conformity	
200   flat surface 100 mm x 100 mm   150   100	Standards	EN 60947-5-2:2007+A1:2012 IEC 60947-5-2:2007 + A1:2012 EN 60947-5-7:2003 IEC 60947-5-7:2003
5	Approvals and certificates	
-50	UL approval	cULus Listed, General Purpose
-100 -150 -200 round bar, Ø 25 mm	CSA approval CCC approval	cCSAus Listed, General Purpose CCC approval / marking not required for products rated ≤36 V
250 200 400 600 800 1000 1200 1400 1600 Distance X [mm]		
$ \qquad \qquad$		

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UB1000-18GM75A-I-V15

A2

A1

object range

**Additional Information** 

A1

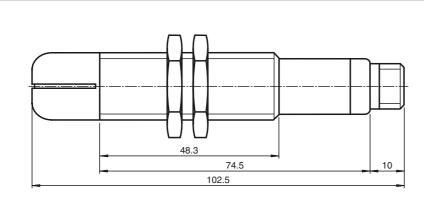
A2

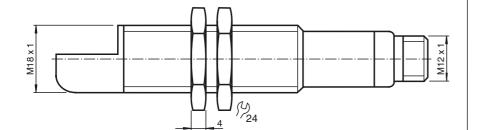
Rising ramp A1 < A2:

Falling ramp A2 < A1:

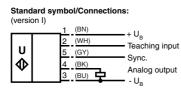
Programming the analog output mode

# Dimensions





# **Electrical Connection**



Core colours in accordance with EN 60947-5-2.

# **Pinout**

**Connector V15** 



# Accessories

**UB-PROG2** Programming unit

**OMH-04** 

Mounting aid for round steel ø 12 mm or sheet 1.5 mm ... 3 mm

**BF 18** Mounting flange, 18 mm

BF 18-F

Plastic mounting adapter, 18 mm

BF 5-30 Universal mounting bracket for cylindrical sensors with a diameter of 5 ... 30 mm

UVW90-K18

Ultrasonic -deflector

V15-G-2M-PVC

Female cordset, M12, 5-pin, PVC cable

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M18K-VE

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# Synchronisation

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. The synchronisation of multiple sensors can be realised as follows:

# **External synchronisation**

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation input starts a measuring cycle. The pulse must have a duration greater than 100  $\mu$ s. The measuring cycle starts with the falling edge of a synchronisation pulse. A low level > 1 s or an open synchronisation input will result in the normal operation of the sensor. A high level at the synchronisation input disables the sensor. Two operating modes are available:

- 1. Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.
- 2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

#### Internal synchronisation

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors will operate in multiplex mode.

The response delay increases according to the number of sensors to be synchronised. Synchronisation cannot be performed during TEACH-IN and vice versa. The sensors must be operated in an unsynchronised manner to teach the evaluation limits.

## Note:

If the option for synchronisation is not used, the synchronisation input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

#### Adjusting the evaluation limits

The ultrasonic sensor features an analogue output with two teachable evaluation limits. These are set by applying the supply voltage  $-U_B$  or  $+U_B$  to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s. LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. The lower evaluation limit A1 is taught with  $-U_B$ , A2 with  $+U_B$ .

- Two different output functions can be set:
- 1. Analogue value increases with rising distance to object (rising ramp)
- 2. Analogue value falls with rising distance to object (falling ramp)
  - Evaluation limits may only be specified within the first 5 minutes after Power on. To modify the evaluation limits later,
  - If the user may specify the desired values only after a new Power On.

# TEACH-IN rising ramp (A2 > A1)

- Position object at lower evaluation limit
- TEACH-IN lower limit A1 with UB
- Position object at upper evaluation limit
- TEACH-IN upper limit A2 with + U<sub>B</sub>

## TEACH-IN falling ramp (A1 > A2):

- Position object at lower evaluation limit
- TEACH-IN lower limit A2 with + U<sub>B</sub>
- Position object at upper evaluation limit
- TEACH-IN upper limit A1 with UB

# **Default setting**

A1:	unusable area
A2:	nominal sensing range
Mode of operation:	rising ramp

## **LED Displays**

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Displays in dependence on operating mode	Red LED	Yellow LED
TEACH-IN evaluation limit		
Object detected	off	flashes
No object detected	flashes	off
Object uncertain (TEACH-IN invalid)	on	off
Normal mode (evaluation range)	off	on
Fault	on	previous state

#### Adjusting the sound cone characteristics:

The ultrasonic sensor enables two different shapes of the sound cone, a wide angle sound cone and a small angle sound cone.

#### 1. Small angle sound cone

- switch off the power supply
- connect the Teach-In input wire to -U<sub>B</sub>
- switch on the power supply
- the red LED flashes once with a pause before the next.
- yellow LED: permanently on: indicates the presence of an object or disturbing object within the sensing range

disconnect the Teach-In input wire from -U<sub>B</sub> and the changing is saved

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# 2. Wide angle sound cone

- · switch off the power supply
- connect the Teach-In input wire with +UB
- ٠ switch on the power supply
- the red LED double-flashes with a long pause before the next.
- ٠ yellow LED: permanently on: indicates an object or disturbing object within the sensing range
- disconnect the Teach-In input wire from  $+ U_{B}$  and the changing is saved ٠

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