





Model Number

UBR250-F77-E2-V31

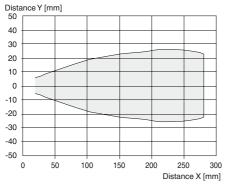
Reflex ultrasonic sensor

Features

- · Miniature design
- Program input
- Degree of protection IP67
- Switching status indicator, yellow LED

Diagrams

Characteristic response curve





Technical data

General specifications	
Sensing range	0 250 mm
Adjustment range	53 250 mm
Standard target plate	20 mm x 20 mm
Transducer frequency	approx. 400 kHz

Nominal ratings
Time delay before availability $t_v \le 150 \text{ ms}$

Limit data

Permissible cable length max. 300 m

Indicators/operating means

LED yellow switching state and flashing: Teach-In

Electrical specifications
Rated operating voltage U_e

Rated operating voltage $\rm U_e$ 24 V DC Operating voltage $\rm U_B$ 20 ... 30 V DC , ripple 10 $\rm \%_{SS}$; 12 ... 20 V DC sensitivity

reduced to 90 %

No-load supply current $I_0 \le 20 \text{ mA}$

Input Input type 1 program input

Level low level : 0 ... 0.7 V (Teach-In active) high level : U_B or open input (Teach-In inactive)

 $\begin{array}{ll} \text{Input impedance} & 16 \text{ k}\Omega \\ \text{Pulse length} & \geq 3 \text{ s} \end{array}$

Output

Output type 1 switch output PNP, NO
Rated operating current I_e 200 mA , short-circuit/overload protected

 $\begin{array}{lll} \mbox{Voltage drop U}_d & \leq 2 \ \mbox{V} \\ \mbox{Switch-on delay t}_{on} & \leq 50 \ \mbox{ms} \\ \mbox{Switching frequency f} & 10 \ \mbox{Hz} \\ \mbox{Off-state current I}_r & \leq 0.01 \ \mbox{mA} \\ \mbox{Temperature influence} & + 0.17 \ \% \mbox{K} \\ \end{array}$

Ambient conditions

Ambient temperature $-25 \dots 70 \, ^{\circ}\text{C} \, (-13 \dots 158 \, ^{\circ}\text{F})$ Storage temperature $-40 \dots 85 \, ^{\circ}\text{C} \, (-40 \dots 185 \, ^{\circ}\text{F})$ Shock resistance $30 \, \text{g} \, , 11 \, \text{ms}$ period

Vibration resistance 10 ... 55 Hz , Amplitude ± 1 mm

Mechanical specifications

Connection type M8 x 1 connector , 4-pin

Degree of protection IP67

Material
Housing Polycarbonate

Transducer epoxy resin/hollow glass sphere mixture; polyurethane foam

max. 0.2 Nm

Installation position any position

Mass 10 g

Tightening torque, fastening screws

Compliance with standards and

directives

Standard conformity

Standards EN 60947-5-2:2007+A1:2012

IEC 60947-5-2:2007 + A1:2012

Approvals and certificates

UL approval cULus Listed, General Purpose

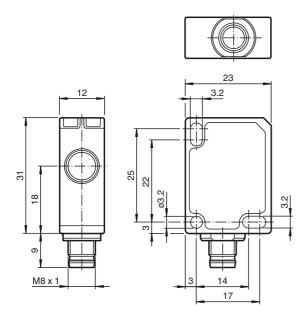
CCC approval / marking not required for products rated ≤36 V

Safety Note



The use of this device in applications, where the safety of persons depends from the devices function, is not allowed!

Dimensions



Description of Sensor Function

The ultrasonic sensor works like a retroreflective sensor. It transmits ultrasonic packages in quick succession and responds to their reflection off a reference object at a defined distance. The distance T to the reference object can be taught in. The sensor has a switch output. This output switches if the reference object is not detected, which happens when another object is located between the sensor and the reference object. The limit of the switching range is derived as follows: T - 5 %.

Notes

- The distance T of the reference object must not be changed during operation. If the distance T changes, it will have to be taught-in again.
- The reference object must not be removed during operation.

Teach-In the Distance to the Reference Object

Proceed as follows to teach in the distance T to the reference object:

- 1. Connect the sensor and turn on the operating voltage.
- Place the reference object at the required distance.
- 3. Connect the teach-in input (ET) to -UB. This can be done using the pushbutton or the con-
 - The LED will start flashing after 3 seconds to indicate that the sensor is ready to start the teach-in process ^(*).
- 4. Disconnect the teach-in input (ET) with -U_B. The distance T to the reference object has now been taught in (*)
- If no object is detected within the sensing range of the sensor, the sensor will start flash-(*) ing at a faster rate. The switching point remains unchanged.

Switching characteristics and display LED

Sensing range			Output	LED	
	Adjustment range				
	Switching area	5%	Reference		
		of	object	-U _B	Off
	•	Т	(position T)	+U _B	On
				+U _R	On

= Object position

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